

2014 Specialist Maths Trial Exam 2 Solutions
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Section 1

1	2	3	4	5	6	7	8	9	10	11
E	B	D	E	D	D	D	D	C	C	D

12	13	14	15	16	17	18	19	20	21	22
C	A	E	D	C	B	A	C	E	A	D

Q1 $\frac{(x-k)^2}{4-k} - \frac{(y-k)^2}{6-k} = \frac{1}{12}$ is a hyperbola

when $4-k > 0$ and $6-k > 0$ OR $4-k < 0$ and $6-k < 0$
 $\therefore k < 4$ OR $k > 6$

D

Q2 $\text{Ran}(-\cos^{-1} x) \subseteq \text{dom}(\sin x), \therefore -\frac{\pi}{2} \leq -\cos^{-1} x \leq \frac{\pi}{2}$

$\frac{\pi}{2} \geq \cos^{-1} x \geq -\frac{\pi}{2}, \frac{\pi}{2} \geq \cos^{-1} x \geq 0, \therefore 0 \leq x \leq 1$

B

Q3 $z = a \left[i + \text{cis} \left(-\frac{2\pi}{3} \right) \right] = a \left[-\frac{1}{2} + \left(1 - \frac{\sqrt{3}}{2} \right) i \right]$

$\text{Arg}(z) = \tan^{-1}(-2 + \sqrt{3}) \approx 2.8798$

Q4 $c = 0$, no asymptote; $c < 0$, 1 asymptote;
 $c = 1$, 2 asymptotes; $c > 0$ and $c \neq 1$, 3 asymptotes

Q5 $\frac{1 - \sin 2x}{1 + \sin 2x} = \frac{(1 - \sin 2x)(1 - \sin 2x)}{(1 + \sin 2x)(1 - \sin 2x)}$
 $= \frac{(1 - \sin 2x)^2}{1 - \sin^2 2x} = \frac{(1 - \sin 2x)^2}{\cos^2 2x}$

$= \left(\frac{1}{\cos 2x} - \frac{\sin 2x}{\cos 2x} \right)^2 = (\sec 2x - \tan 2x)^2$

D

Q6 The graph is the dilation of $y = \cos^{-1} x$ from the x and y axis by factors of $\frac{1}{2}$ and 2 respectively, followed by translation

of 1 unit to the left and translation of $\frac{\pi}{4}$ downwards.

$y = \cos^{-1} x \rightarrow 2y = \cos^{-1} \left(\frac{x}{2} \right) \rightarrow 2 \left(y + \frac{\pi}{4} \right) = \cos^{-1} \left(\frac{x+1}{2} \right)$

D

Q7 $\arg(z_1 z_2) = \arg(z_1) + \arg(z_2) = \frac{2\pi}{3} + \frac{7\pi}{6} = \frac{11\pi}{6} = \arg z_6$

D

Q8 $(x + yi)^2 = n - ni, (x^2 - y^2) + 2xyi = n - ni$

$\therefore x^2 - y^2 = n$ and $2xy = -n$

$\therefore \left(\frac{-n}{2y} \right)^2 - y^2 = n, n^2 - 4(y^2)^2 = 4ny^2, 4(y^2)^2 + 4ny^2 - n^2 = 0$

$y^2 = \frac{n(\sqrt{2}-1)}{2} = \frac{n}{2(\sqrt{2}+1)}$

D

Q9

C

Q10 $y = \tan^{-1} x, \frac{dy}{dx} = \frac{1}{1+x^2}$

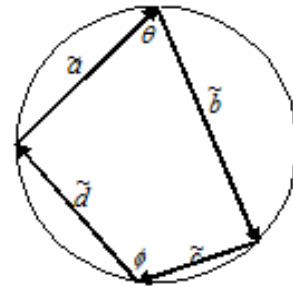
At $x = a, y = \tan^{-1} a$ and $m = \frac{dy}{dx} = \frac{1}{1+a^2}$

$\therefore (a, \tan^{-1} a)$ is a point on the tangent line $y = \frac{1}{1+a^2} x + \frac{\pi}{4}$

$\therefore \tan^{-1} a = \frac{a}{1+a^2} + \frac{\pi}{4}, \therefore a \approx 2.264$

C

Q11



$\theta + \phi = \pi, \theta = \pi - \phi$ (cyclic quadrilateral)

D

$\frac{\tilde{a} \cdot \tilde{b}}{|\tilde{a}| |\tilde{b}|} = \cos(\pi - \theta) = -\cos \theta, \frac{\tilde{c} \cdot \tilde{d}}{|\tilde{c}| |\tilde{d}|} = \cos(\pi - \phi) = \cos \theta$

E

$\frac{\tilde{a} \cdot \tilde{b}}{|\tilde{a}| |\tilde{b}|} + \frac{\tilde{c} \cdot \tilde{d}}{|\tilde{c}| |\tilde{d}|} = -\cos \theta + \cos \theta = 0$

$\therefore \frac{\tilde{a} \cdot \tilde{b} |\tilde{c}| |\tilde{d}| + |\tilde{a}| |\tilde{b}| \tilde{c} \cdot \tilde{d}}{|\tilde{a}| |\tilde{b}| |\tilde{c}| |\tilde{d}|} = 0$

$\therefore \tilde{a} \cdot \tilde{b} |\tilde{c}| |\tilde{d}| + |\tilde{a}| |\tilde{b}| \tilde{c} \cdot \tilde{d} = 0$

D

D

Q12 $\tilde{a} \cdot \tilde{b} = 0, \therefore \tilde{a} \perp \tilde{b}, \tilde{c}$ is parallel to $\tilde{a}, \therefore \tilde{c} \perp \tilde{b}$

$\tilde{c} = x\tilde{i} + y\tilde{j} + z\tilde{k}$ and $\sqrt{x^2 + y^2 + z^2} = 1$

$\tilde{c} = m\tilde{a} = m\tilde{i} + m\sqrt{2}\tilde{j} - m\tilde{k}, \therefore \sqrt{m^2 + 2m^2 + (-m)^2} = 1$

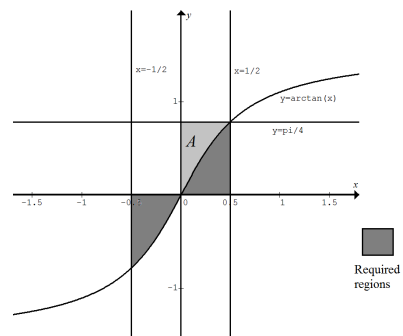
$\therefore 4m^2 = 1, m = \pm \frac{1}{2}, \tilde{c} = \frac{1}{2}\tilde{i} + \frac{1}{\sqrt{2}}\tilde{j} - \frac{1}{2}\tilde{k}$

C

Q13 Three non-parallel 3-D vectors cannot be dependent.

A

Q14



Area of the required regions $= 2 \left(\frac{\pi}{4} \times \frac{1}{2} - A \right) = \frac{\pi}{4} - 2A$

E

Q15 $f(x) = \frac{d}{dx} \int f(x) dx$

One of the x -intercepts of $f(x)$ corresponds to the local minimum of the anti-derivative of $f(x)$. The second x -intercept of $f(x)$ is a turning point corresponding to the stationary point of inflection of the anti-derivative of $f(x)$.

D

Q16 $a \sin^{-1} x + 2b \cos^{-1} x = a \sin^{-1} x + 2b \left(\frac{\pi}{2} - \sin^{-1} x \right)$
 $= a \sin^{-1} x - 2b \sin^{-1} x + b\pi = b\pi - (2b - a) \sin^{-1} x$

C

Q17 $y = \int_{1.7}^{4.6} \cos \sqrt{x^2 + 1} dx + 5.24 \approx 3.20$

B

Q18 $\int \frac{1}{1+e^t} dt = \int \frac{e^{-t}}{e^{-t}+1} dt$, let $u = e^{-t} + 1$, $\frac{du}{dt} = -e^{-t}$

$\therefore \int \frac{1}{1+e^t} dt = \int -\frac{du}{u} = -\log_e u + c = -\log_e (e^{-t} + 1) + c$

$\therefore s = \int_1^2 \frac{1}{1+e^t} dt = \left[-\log_e (e^{-t} + 1) \right]_1^2 = \left[\log_e \frac{1}{e^{-t} + 1} \right]_1^2$
 $= \left[\log_e \frac{e^t}{1+e^t} \right]_1^2$

A

Q19 $\tilde{r} = \left(\frac{t^3}{3} - t^2 \right) \tilde{i}$, $\tilde{v} = (t^2 - 2t) \tilde{i}$, $\tilde{a} = (2t - 2) \tilde{i}$

The particle reverses direction when $\tilde{v} = \tilde{0}$ at $t = 2$.

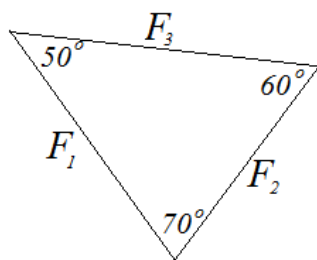
$\therefore \tilde{a} = 2 \tilde{i}$

C

Q20 The reading on the bathroom scale is lowered. The lift can be moving upwards with decreasing speed, or moving downwards with increasing speed.

E

Q21



Q22 Acceleration of the particle is zero, $\therefore$ the vector sum of the only two forces, the weight force and the reaction force, on the particle is zero, $\therefore$ the reaction force is equal and opposite to the weight force.

D

Section 2

Q1a $9(y-b)^2 = 4(x-a)^2 - 36$, $y-b = \pm \frac{2}{3} \sqrt{(x-a)^2 - 9}$

$\frac{dy}{dx} = \pm \frac{2(x-a)}{3\sqrt{(x-a)^2 - 9}}$

Q1b $y-b = \pm \frac{2}{3} \sqrt{(x-a)^2 - 9}$ and $\frac{dy}{dx} = \pm \frac{2(x-a)}{3\sqrt{(x-a)^2 - 9}}$

When $a=b=0$ and at $x=k$,

$y = \pm \frac{2}{3} \sqrt{k^2 - 9}$ and $\frac{dy}{dx} = \pm \frac{2k}{3\sqrt{k^2 - 9}}$

Tangent: $y - \left(\pm \frac{2}{3} \sqrt{k^2 - 9} \right) = \pm \frac{2k}{3\sqrt{k^2 - 9}} (x - k)$

$\therefore y = \pm \frac{2k}{3\sqrt{k^2 - 9}} (x - k) \pm \frac{2}{3} \sqrt{k^2 - 9}$

$y = \pm \frac{2k}{3\sqrt{k^2 - 9}} x \pm \frac{6}{\sqrt{k^2 - 9}}$

Q1c y-intercepts: $x=0$, $y = \pm \frac{6}{\sqrt{k^2 - 9}}$

As $k \rightarrow \infty$, $y \rightarrow 0$, the same y-intercept $(0, 0)$

Q1d Asymptotes of $4x^2 - 9y^2 = 36$:

$\frac{x^2}{9} - \frac{y^2}{4} = 1$, the asymptotes are $y = \pm \frac{2}{3} x$

The tangents: $y = \pm \frac{2k}{3\sqrt{k^2 - 9}} x \pm \frac{6}{\sqrt{k^2 - 9}}$

$y = \pm \frac{\frac{2k}{k}}{3\sqrt{k^2 - 9}} x \pm \frac{6}{\sqrt{k^2 - 9}}$, $y = \pm \frac{2}{3\sqrt{k^2 - 9}} x \pm \frac{6}{\sqrt{k^2 - 9}}$

$y = \pm \frac{2}{3\sqrt{1 - \frac{9}{k^2}}} x \pm \frac{6}{\sqrt{k^2 - 9}}$

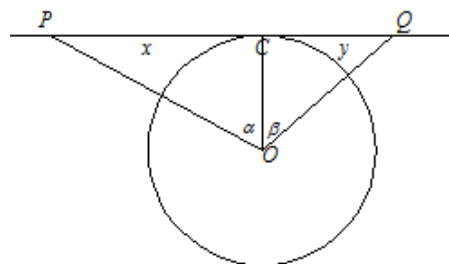
As $k \rightarrow \infty$, $\sqrt{1 - \frac{9}{k^2}} \rightarrow 1$, $\frac{6}{\sqrt{k^2 - 9}} \rightarrow 0$

$\therefore$ the tangents approach $y = \pm \frac{2}{3} x$, the asymptotes of

$4x^2 - 9y^2 = 36$.

A

Q2a Let $\theta = \alpha + \beta$



$\tan \theta = \tan(\alpha + \beta) = \frac{\tan \alpha + \tan \beta}{1 - \tan \alpha \tan \beta} = \frac{x + y}{1 - xy}$

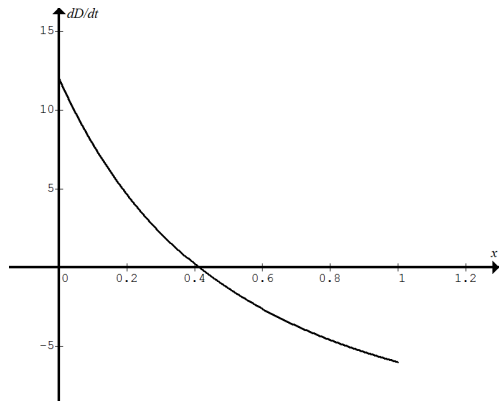
Q2b $\theta = \frac{\pi}{4}$, $\frac{x+y}{1-xy} = 1$, $y = \frac{1-x}{1+x}$, $\frac{dy}{dx} = -\frac{2}{(1+x)^2}$

When $x=1$, $\frac{dy}{dx} = -\frac{1}{2}$,

$\frac{dy}{dt} = \frac{dy}{dx} \times \frac{dx}{dt} = -\frac{1}{2} \times (-12) = 6 \text{ km h}^{-1}$

Q2ci Let $D = x + y$, $\frac{dD}{dt} = \frac{dx}{dt} + \frac{dy}{dx} \times \frac{dx}{dt} = \frac{dx}{dt} \left(1 + \frac{dy}{dx} \right)$
 $= -12 \left(1 - \frac{2}{(1+x)^2} \right) = \frac{24}{(1+x)^2} - 12$

Q2cii



When $x > 0.41$ approximately, $\frac{dD}{dt} < 0$, i.e. D decreases with t . When $x < 0.41$ approximately, $\frac{dD}{dt} > 0$, i.e. D increases with t .

Q2d $\tan \theta = \frac{x+y}{1-xy}$ and $x+y = \frac{2\sqrt{3}}{3} = \frac{2}{\sqrt{3}}$

$\therefore y = \frac{2}{\sqrt{3}} - x$ and $\tan \theta = \frac{\frac{2}{\sqrt{3}}}{1 - x\left(\frac{2}{\sqrt{3}} - x\right)} = \frac{2}{\sqrt{3} - 2x + \sqrt{3}x^2}$

$\frac{d}{dx}(\tan \theta) = \frac{d}{dx} \left(\frac{2}{\sqrt{3} - 2x + \sqrt{3}x^2} \right)$

$\frac{d \tan \theta}{d \theta} \times \frac{d \theta}{dx} = \frac{-2(-2 + 2\sqrt{3}x)}{(\sqrt{3} - 2x + \sqrt{3}x^2)^2}$

Let $\frac{d \theta}{dx} = 0$, $\therefore \frac{-2(-2 + 2\sqrt{3}x)}{(\sqrt{3} - 2x + \sqrt{3}x^2)^2} = 0$, $-2 + 2\sqrt{3}x = 0$

$\therefore x = \frac{1}{\sqrt{3}}$ and $y = \frac{1}{\sqrt{3}}$, $\therefore \tan \theta = \sqrt{3}$, $\theta = \frac{\pi}{3}$

Q2e When $\theta = \frac{\pi}{3}$, $\frac{d \theta}{dx} = 0$, $\therefore \frac{d \theta}{dt} = \frac{d \theta}{dx} \times \frac{dx}{dt} = 0$

Q3a $\tilde{r}(t) = \int \tilde{v} dt = \int \left(\frac{1}{1+t} \tilde{i} + \frac{1}{1+t^2} \tilde{j} \right) dt$
 $= (\log_e(1+t)) \tilde{i} + (\tan^{-1} t) \tilde{j}$, given $\tilde{r}(0) = \tilde{0}$

Q3b $x = \log_e(1+t)$, $t = e^x - 1$

$y = \tan^{-1} t$, $t = \tan y$ $\therefore \tan y = e^x - 1$

Q3ci $\tan y = e^x - 1$, $\frac{d}{dx}(\tan y) = \frac{d}{dx}(e^x - 1)$

$\frac{d}{dy}(\tan y) \times \frac{dy}{dx} = e^x$, $\sec^2 y \times \frac{dy}{dx} = e^x$, $\frac{dy}{dx} = e^x \cos^2 y$

Note: $y \neq \frac{\pi}{2}$, $\therefore \frac{dy}{dx} \neq 0$

$\frac{d^2 y}{dx^2} = e^x (2 \cos y)(-\sin y) \frac{dy}{dx} + e^x \cos^2 y$

$\therefore \frac{d^2 y}{dx^2} = -e^x (2 \sin y \cos y) \frac{dy}{dx} + \frac{dy}{dx}$

$= \frac{dy}{dx} (1 - e^x \sin 2y)$

For points of inflection, $\frac{d^2 y}{dx^2} = 0$ $\therefore \frac{dy}{dx} (1 - e^x \sin 2y) = 0$

$\therefore 1 - e^x \sin 2y = 0$, $e^x \sin 2y = 1$, $e^x \sin 2(\tan^{-1}(e^x - 1)) = 1$

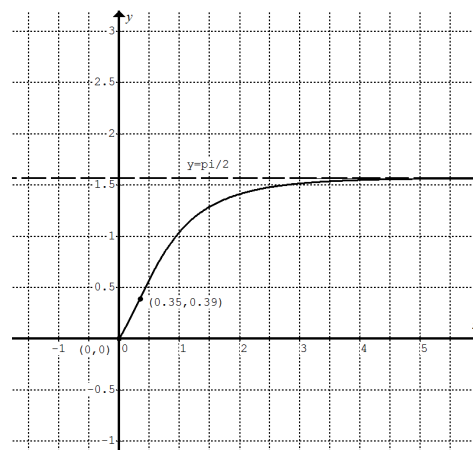
By CAS, $x \approx 0.35$ (0.34657) and $y = \tan^{-1}(e^x - 1) \approx 0.39$

Q3cii $t = e^x - 1 \approx 0.41$ (0.4142)

Q3ciii $\tilde{v}(0.4142) = \frac{1}{1+0.4142} \tilde{i} + \frac{1}{1+0.4142^2} \tilde{j}$
 $= 0.7071 \tilde{i} + 0.8536 \tilde{j}$

Speed $= \sqrt{0.7071^2 + 0.8536^2} \approx 1.11$

Q3d



Q4a $P(x) = (x-5)(x-3)(x-1)(x+1) - c$

Let $f(x) = (x-5)(x-3)(x-1)(x+1) = x^4 - 8x^3 + 14x^2 + 8x - 15$

The absolute minimum of $f(x)$ is -16 .

For $P(x)$ to have non-real roots (i.e. no x -intercepts), $P(x) > 0$ for $x \in \mathbb{R}$, $\therefore c < -16$

Q4b $P(x) = (x-5)(x-3)(x-1)(x+1) - 105 = 0$

$(x-5)(x+1)(x-3)(x-1) - 105 = 0$

$(x^2 - 4x - 5)(x^2 - 4x + 3) - 105 = 0$ and let $p = x^2 - 4x$

$\therefore (p-5)(p+3) - 105 = 0$, $p^2 - 2p - 120 = 0$

$(p-12)(p+10) = 0$, $\therefore x^2 - 4x - 12 = 0$ or $x^2 - 4x + 10 = 0$

$\therefore x = -2, 6$, or $x = 2 \pm \sqrt{6}i$

Q4ci As in Q4b with $c = -17$, $(p-5)(p+3)+17=0$

$$\therefore p^2 - 2p + 2 = 0, \therefore p = 1-i \text{ or } p = 1+i$$

$$\therefore x^2 - 4x - (1-i) = 0 \text{ or } x^2 - 4x - (1+i) = 0$$

$$x = 2 \pm \sqrt{5-i} \text{ or } x = 2 \pm \sqrt{5+i}$$

$$x = 2 \pm (2.2471 - 0.2225i) \text{ or } x = 2 \pm (2.2471 + 0.2225i)$$

$$x = 4.2471 - 0.2225i, -0.2471 + 0.2225i, 4.2471 + 0.2225i \\ \text{or } -0.2471 - 0.2225i$$

The two pairs of conjugate roots are:

$$4.2471 \pm 0.2225i \text{ and } -0.2471 \pm 0.2225i$$

Q4cii The roots are equidistant from $2+0i$ in the Argand plane, $\therefore$ the centre of the circle is $2+0i$ (or $(2, 0)$) and the

$$\text{radius is } \left| \sqrt{5+i} \right| = \left| \sqrt{\sqrt{5^2+1^2}} \operatorname{cis} \theta \right| = \left| \sqrt[4]{26} \operatorname{cis} \frac{\theta}{2} \right| = \sqrt[4]{26}$$

$$\text{Q5a Force of friction} = \mu N = 0.30 \times 1500 \times 9.8 = 4410 \text{ N}$$

Q5b Friction force F_f between the tyres and the ground is the driving force.

$$F_f - 200 - 4410 = (3000 + 150 + 1500) \times 0.20, F_f = 5540 \text{ N}$$

Q5c The log has the same acceleration as the truck, 0.20 m s^{-2} .

Q5d Motion of the truck:

$$5540 - 200 - T_1 = 3000 \times 0.20, T_1 = 4740 \text{ N}$$

Motion of the log:

$$T_2 - 4410 = 1500 \times 0.20, T_2 = 4710 \text{ N}$$

Maximum tension of 4740 N at the truck end of the rod, and minimum tension of 4710 N at the log end.

Q5e When the truck moves at constant speed in a straight line, the driving force equals to the friction between the log and the ground, and the total of air resistance and other resistive forces.

$$F_f = 4410 + 200 = 4610 \text{ N}$$

Q5f Uniform tension of 4410 N in the rod

Q5g Trucks slows down at 0.10 m s^{-2} :

$$F_f - 200 - 4410 = (3000 + 150 + 1500) \times (-0.10), F_f = 4145 \text{ N}$$

Motion of the truck:

$$4145 - 200 - T_1 = 3000 \times (-0.10), T_1 = 4245 \text{ N}$$

Motion of the log:

$$T_2 - 4410 = 1500 \times (-0.10), T_2 = 4260 \text{ N}$$

The tension in the rod is greater at the log end than the tension at the truck end.

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