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## VCE Specialist Mathematics ½ Transformations II [4.3] Workbook

### Outline:

<u>Recap of [4.2] Transformations</u>	Pg 2-7	<u>Rotations</u> ➤ Rotations Around the Origin ➤ Rotations Around Any Point	Pg 11-20
<u>Transformations of Graphs</u>	Pg 8-10	<u>General Reflections</u> ➤ Reflections Across a Line $y = mx$ ➤ Reflections Around a Line $y = mx + c$	Pg 21-28

### Learning Objectives:

- SM12 [4.3.1] - Transformations of Graphs
- SM12 [4.3.2] - Rotations Around Points
- SM12 [4.3.3] - Reflections in Lines

## Section A: Recap of [4.2] Transformations

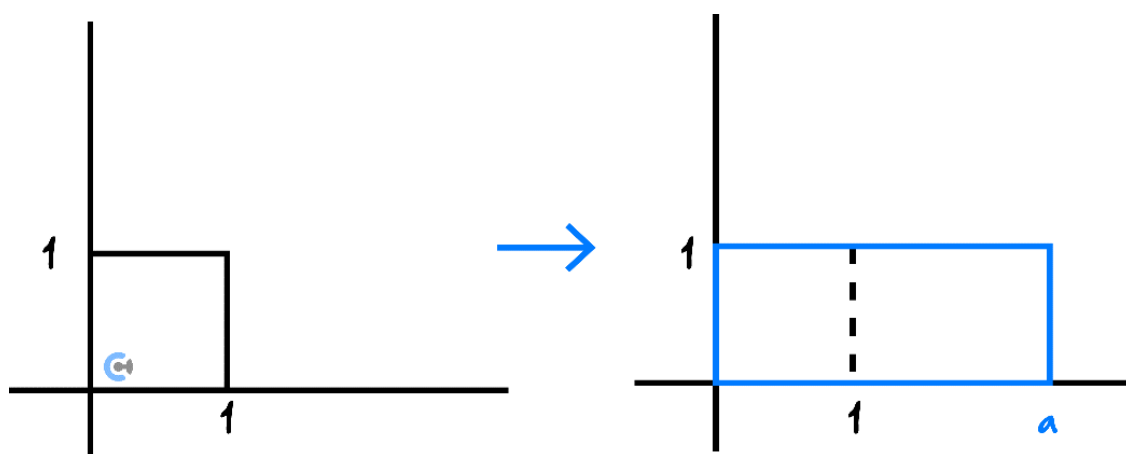
*Let's do a quick recap of what we did last week!*

### Linear Transformations

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = A \cdot \begin{bmatrix} x \\ y \end{bmatrix}$$

- The  $(x', y)$  represents the new points and is called an \_\_\_\_\_.
- Original point  $(x, y)$  is called the \_\_\_\_\_.
- $A$  is the transformation matrix.

### Dilation from the y-axis



**Dilation by a factor  $a$  from the y-axis**

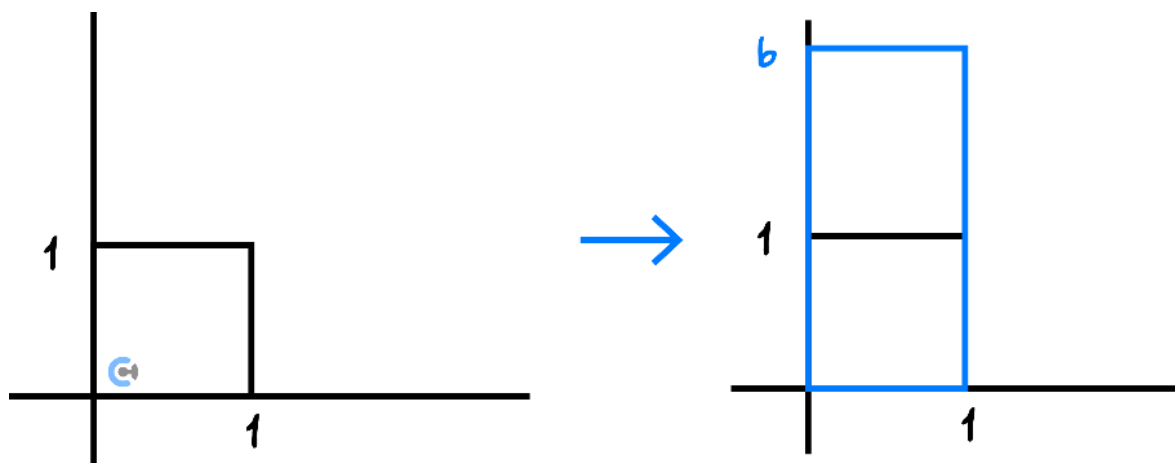
- Dilation from the y-axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} a & 0 \\ 0 & 1 \end{bmatrix}$$

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### Dilation from the $x$ -axis



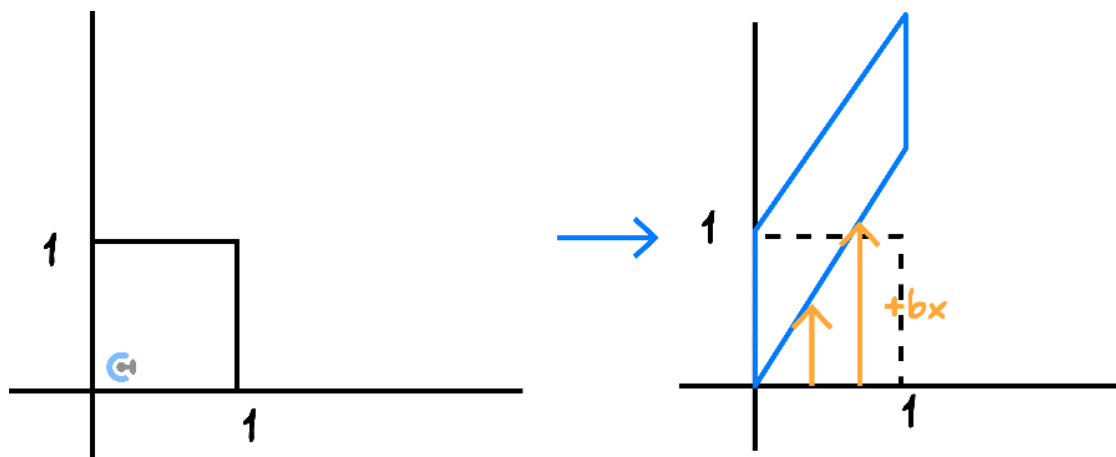
**Dilation by a factor  $b$  from the  $x$ -axis**

➤ Dilation from the  $x$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ 0 & b \end{bmatrix}$$



### Shear Parallel to the $y$ -axis



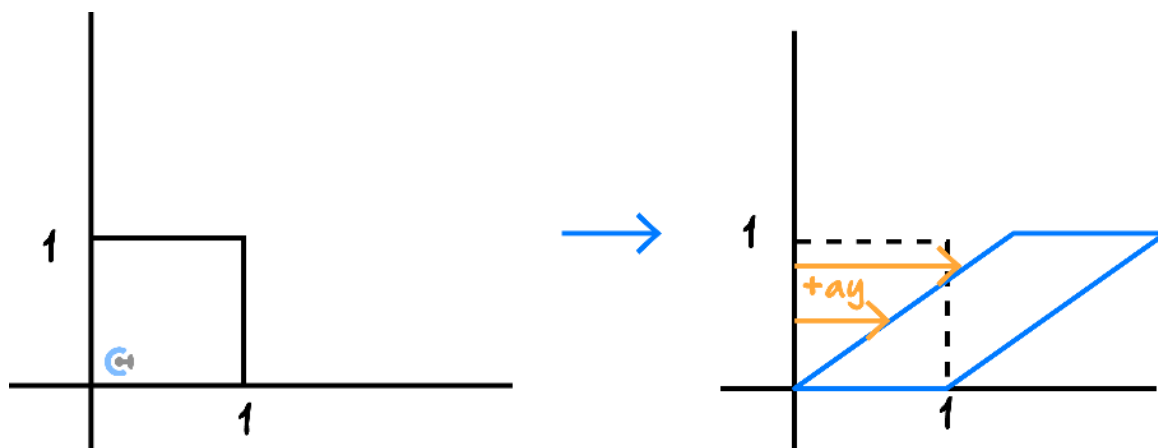
**Shear of a factor  $b$  parallel to the  $y$ -axis**

➤ Shear parallel to  $y$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ b & 1 \end{bmatrix}$$



### Shear Parallel to the $x$ -axis



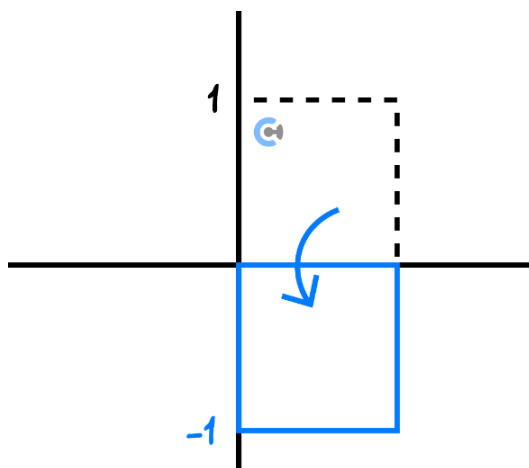
### Shear of a factor $a$ parallel to the $x$ -axis

➤ Shear parallel to  $x$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}$$



### Reflection Around $x$ -axis



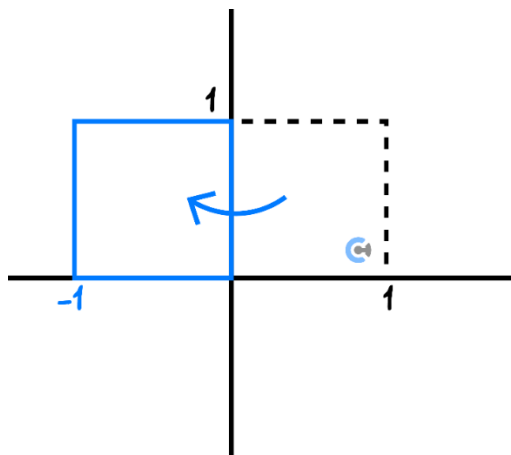
### Reflection in the $x$ -axis

➤ Reflection in the  $x$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$



### Reflection Around y-axis



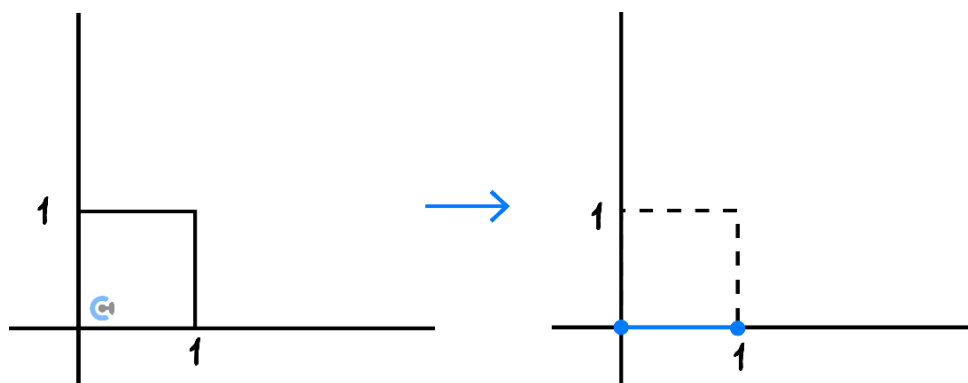
### Reflection in the y-axis

- Reflection in the y-axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$



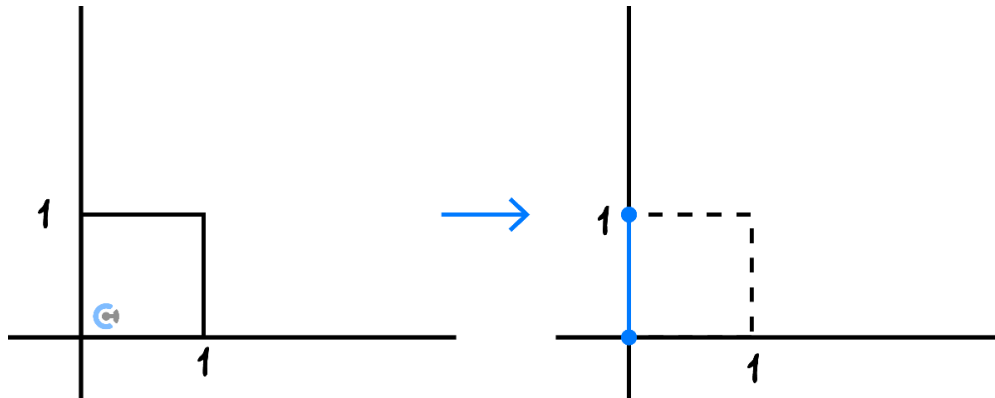
### Projections



### Projection onto x-axis

- The \_\_\_\_\_ becomes 0.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$



Projection onto  $y$ -axis

► The \_\_\_\_\_ becomes 0.

$$\text{Transformation Matrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Space for Personal Notes

**Question 1 Walkthrough.**

- a. State the transformation matrix for the shear of a factor 2 parallel to the  $y$ -axis and dilation by a factor 3 from the  $x$ -axis.
- b. Apply the transformation matrix found in **part a.** to the coordinate  $(3, 1)$ .

Space for Personal Notes

**Question 2**

- a. State the transformation matrix for dilation by a factor 2 from the  $y$ -axis and the shear of a factor 3 parallel to the  $x$ -axis.
- b. Apply the transformation matrix found in **part a.** to the coordinate  $(2, 4)$ .

**Space for Personal Notes**



## Section B: Transformations of Graphs

Discussion: If we can transform points, how can we transform functions/graphs?



### Transformation of Functions/Graphs



$$y = f(x) \rightarrow y' = f(x')$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = T \left( \begin{bmatrix} x \\ y \end{bmatrix} \right)$$

➤ **Steps:**

1. Find  $x' = f(x)$  and  $y' = g(y)$ .
2. Rearrange and make  $x, y$  the subject.
3. Substitute into the original function.
4. Remove ' on the variables.

Space for Personal Notes

**Question 3 Walkthrough.**

**a.** State the transformation matrix for dilation by a factor  $\frac{1}{2}$  from the  $y$ -axis and reflection around the  $x$ -axis.

**b.** Find the image of  $(x, y)$  under the transformation described in **part a**.

Consider a function  $f(x) = \sqrt{x+3} - 1$ . It is known that all the points of  $f(x)$  have been transformed by the transformation matrix found in **part a**.

**c.** Find the transformed graph.



*Your turn!*

#### Question 4

a. State the transformation matrix for dilation by a factor of 5 from the  $y$ -axis and a reflection around the  $y$ -axis.

b. Find the image of  $(x, y)$  under the transformation described in **part a**.

Consider a function  $f(x) = (x - 4)^2 + 3$ .

It is known that all the points of  $f(x)$  have been transformed by the transformation matrix found in **part a**.

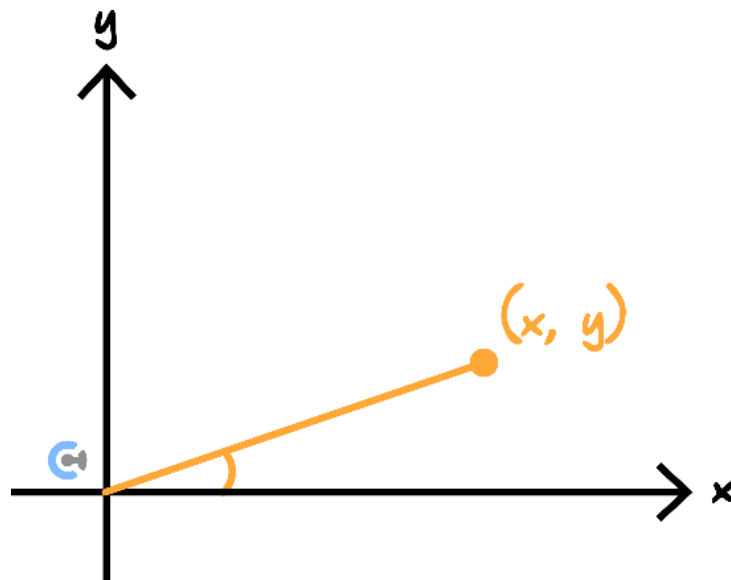
c. Find the transformed graph.

## Section C: Rotations

### Sub-Section: Rotations Around the Origin

*How do we rotate a point around the origin?*

#### Rotation Around the Origin



Rotation  $\theta$  in the Anticlockwise Direction

$$\text{Transformation Matrix} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

Space for Personal Notes

**Question 5 Walkthrough.**

- a. State the transformation matrix for rotation around the origin  $60^\circ$  anticlockwise.
- b. Hence, find the image of  $(3, 1)$  after it has been rotated around the origin  $60^\circ$  anticlockwise.

Space for Personal Notes

### Question 6

- a.** State the transformation matrix for rotation around the origin  $30^\circ$  clockwise.
- b.** Hence, find the image of  $(1, 2)$  after it has been rotated around the origin  $30^\circ$  clockwise.

**NOTE:** If the angle is clockwise, we measure it negatively.



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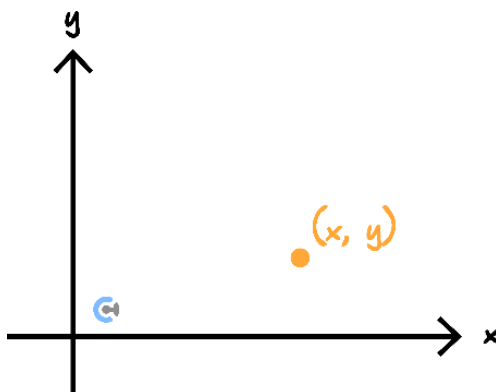
*How does this work?*



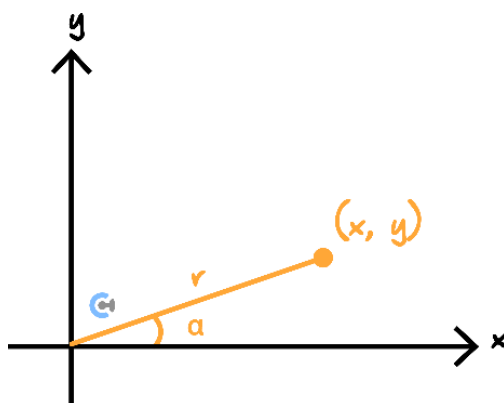
**Exploration: Understanding Rotations Around the Origin**



- Consider a pre-image  $(x, y)$ .



- Let's say the point  $(x, y)$  \_\_\_\_\_ is away from the origin and has an angle of \_\_\_\_\_ anticlockwise from the  $x$ -axis.



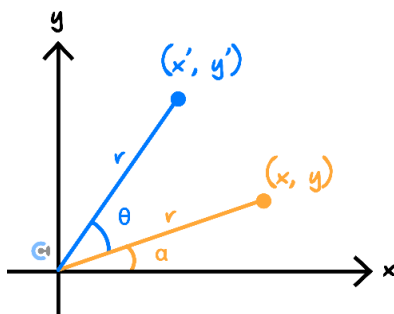
- Using SOHCAHTOA, how can we define  $x$  and  $y$  in terms of  $r$  and  $\alpha$ ?

$$x = \underline{\hspace{2cm}}$$

$$y = \underline{\hspace{2cm}}$$

- What happens when we rotate  $\theta$  anticlockwise around the origin?

Let's visualise the diagram together.



- Using SOHCAHTOA, how can we define  $x'$  and  $y'$  in terms of  $r$  and  $\alpha$ ?

$$x' = \underline{\hspace{2cm}}$$

$$y' = \underline{\hspace{2cm}}$$

- Using the compound angle formulas, expand the following and substitute in the original  $x$  and  $y$ !

$$x' = \underline{\hspace{2cm}}$$

$$= \underline{\hspace{2cm}}$$

$$= \underline{\hspace{2cm}}$$

$$y' = \underline{\hspace{2cm}}$$

$$= \underline{\hspace{2cm}}$$

$$= \underline{\hspace{2cm}}$$

- Hence, in summary:

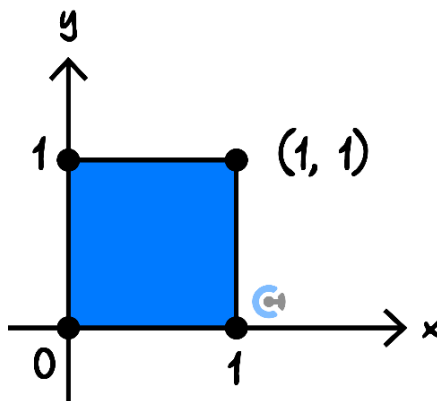
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \cos(\theta) - y \sin(\theta) \\ x \sin(\theta) + y \cos(\theta) \end{bmatrix} = \begin{bmatrix} \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$





**REMINDER: Determinant of Transformation Matrix:**

- Given that  $A$  = Transformation matrix.



- The unit square was used to visualise how a transformation affects different points.

$$\text{Area of the image} = |\det(A)| \times \text{Area of the pre image}$$

- Determinant of the transformation matrix tells us how the area of the unit circle changes.

**Discussion:** What would the determinant of the rotation matrix be?



**Exploration: Determinant of the Rotation Matrix**

- Consider the rotation transformation matrix:

$$\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

- What does the determinant equal to? Evaluate it using algebra!



## Sub-Section: Rotations Around Any Point

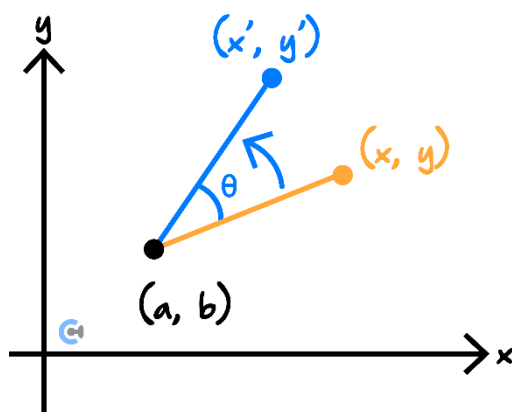
**Discussion:** Since we know how to rotate around the origin, how can we rotate around any point  $(a, b)$ ?



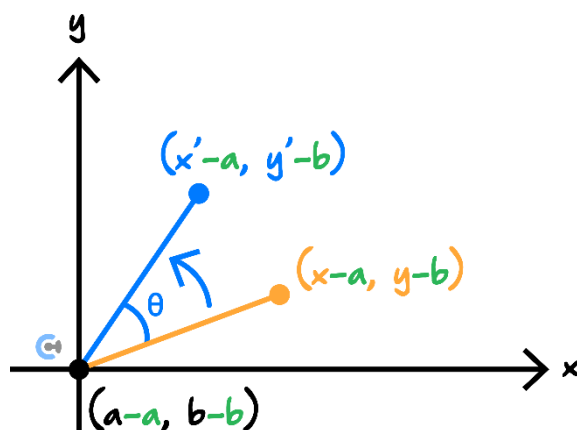
### Rotations Around Any Point $(a, b)$



- Consider the rotation  $\theta$  around the point  $(a, b)$  in the anticlockwise direction.



- Since we know how to rotate from the origin, let us translate ourselves to the origin!



➤ How do we go from  $(x - a, y - b)$  to  $(x' - a, y' - b)$ ?

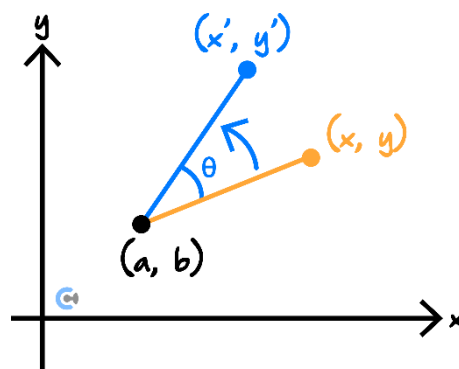
$$\begin{bmatrix} x' - a \\ y' - b \end{bmatrix} = \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \begin{bmatrix} x - a \\ y - b \end{bmatrix}$$

➤ Now, expand the matrices and make  $\begin{bmatrix} x' \\ y' \end{bmatrix}$  the subject!

$$\begin{bmatrix} x' \\ y' \end{bmatrix} - \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \right)$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \right) + \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix}$$

### Rotation Around Any Point $(a, b)$



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} a \\ b \end{bmatrix} \right) + \begin{bmatrix} a \\ b \end{bmatrix}$$

➤ The idea is that we:

1. Translate the points by  $(-a, -b)$  so that the centre becomes the origin.
2. Rotate the point around the origin using the transformation matrix  $\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$ .
3. Translate the points by  $(a, b)$  so that we go back to  $(a, b)$  being the centre.

**Question 7 Walkthrough.**

State the image of  $(1, 1)$  after the rotation around the point  $(2, 1)$ ,  $60^\circ$  anticlockwise.

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**Question 8**

State the image of  $(4, 2)$  after the rotation around the point  $(-1, 1)$ ,  $30^\circ$  anticlockwise.

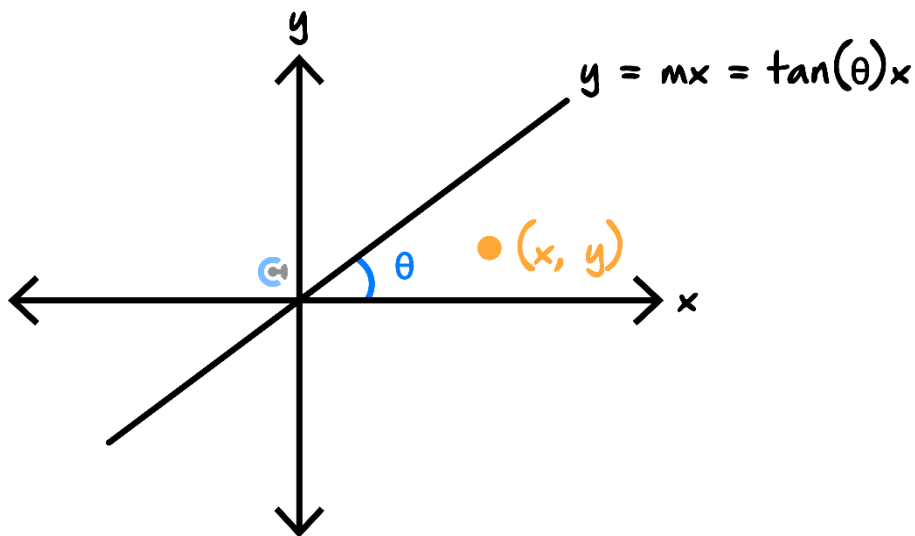
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## Section D: General Reflections

### Sub-Section: Reflections Across a Line $y = mx$

*How do we reflect a point around  $y = mx$ ?*

#### Reflections Across a Line $y = mx$



Reflection around  $y = mx = \tan(\theta)x$

➤  $\theta$  is the angle the reflection line meets with the  $x$ -axis.

$$\text{Transformation Matrix} = \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix}$$

Space for Personal Notes

**Question 9 Walkthrough.**

- a. State the transformation matrix for the reflection around  $y = \frac{1}{\sqrt{3}}x$ .
- b. Hence, find the image of  $(3, 1)$  after it has been reflection around  $y = \frac{1}{\sqrt{3}}x$ .

**Space for Personal Notes**

### Question 10

- a.** State the transformation matrix for the reflection around  $y = -\sqrt{3}x$ .
- b.** Hence, find the image of  $(-1, 1)$  after it has been reflection around  $y = -\sqrt{3}x$ .

**NOTE:** If the angle is clockwise, we measure it negatively.



### Space for Personal Notes



## What about reflection around $y = x$ ?



### Exploration: Understanding Reflection Around $y = x$

- Consider a transformation matrix for reflection around  $y = x$ .
- What angle does  $y = x$  make with the  $x$ -axis?

 \_\_\_\_\_

 Hence, construct the transformation matrix below.

$$\begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix} = \begin{bmatrix} & \\ & \end{bmatrix}$$

- Apply the transformation to the point  $(x, y)$ . What do you see?

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} & \\ & \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} =$$

- As you can see, \_\_\_\_\_ swaps!
- That makes sense as \_\_\_\_\_ relation is found by reflecting around  $y = x$ .

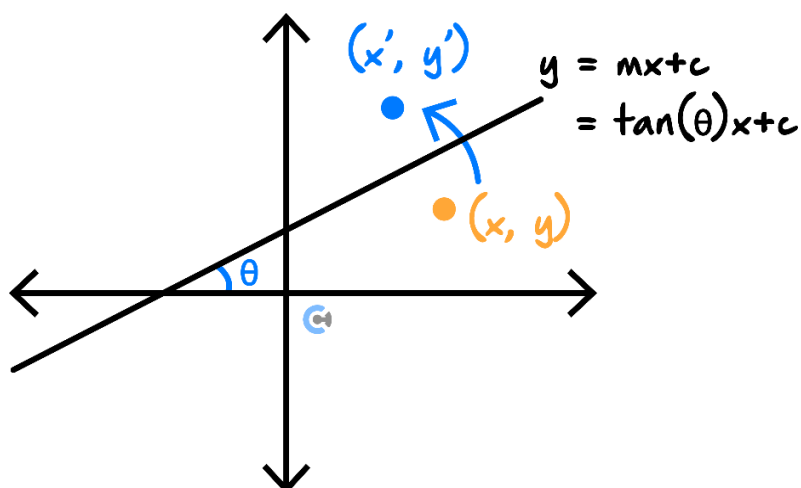
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## Sub-Section: Reflections Around a Line $y = mx + c$

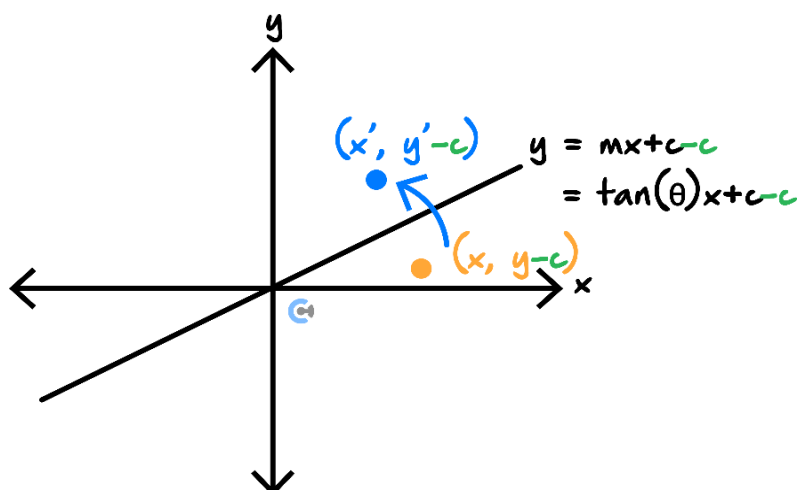
**Discussion:** Since we know how to reflect around  $y = mx$ , how can we reflect around  $y = mx + c$ ?

**Exploration:** Reflection Around  $y = mx + c$

➤ Consider the reflection around  $y = mx + c$ .



➤ Since we know how to reflect around  $y = mx$ , let's translate it down by  $c$ .



➤ How do we go from  $(x, y - c)$  to  $(x', y' - c)$ ?

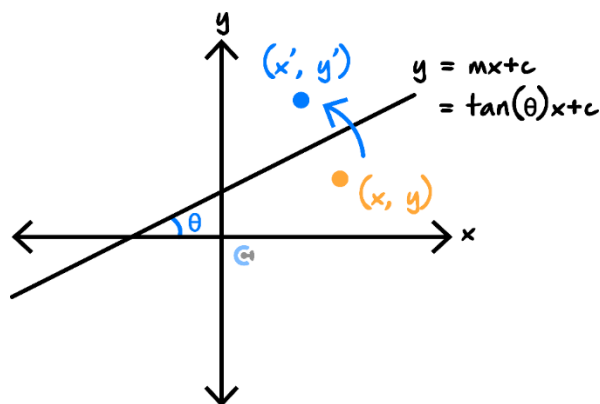
$$\begin{bmatrix} x' \\ y' - c \end{bmatrix} = \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \begin{bmatrix} x \\ y - c \end{bmatrix}$$

➤ Now, expand the matrices and make  $\begin{bmatrix} x' \\ y' \end{bmatrix}$  the subject!

$$\begin{bmatrix} x' \\ y' \end{bmatrix} - \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} = \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \right)$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \right) + \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix}$$

### Reflection Across a Line $y = mx + c$



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} 0 \\ c \end{bmatrix} \right) + \begin{bmatrix} 0 \\ c \end{bmatrix}$$

➤ The idea is that we:

1. Translate the points by  $(0, -c)$  so that the line  $y = mx + c$  becomes  $y = mx$ .
2. Reflect the point around  $y = mx$  using the transformation matrix  $\begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix}$ .
3. Translate the points by  $(0, c)$  so that we go back to the line  $y = mx + c$ .



**Question 11 Walkthrough.**

State the image of  $(1, 1)$  after the reflection around the line  $y = \sqrt{3}x + 1$ .

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**Question 12**

State the image of  $(2, -1)$  after the reflection around the line  $y = \frac{1}{\sqrt{3}}x - 1$ .

Space for Personal Notes



## Contour Check

### □ Learning Objective: [4.3.1] - Transformations of graphs

#### Key Takeaways

#### □ Transformation of Functions/Graphs:

$$y = f(x) \rightarrow y' = f(x')$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = T \left( \begin{bmatrix} x \\ y \end{bmatrix} \right)$$

#### ○ Steps:

1. Find  $x' = f(x)$  and  $y' = g(y)$ .
2. Rearrange and make \_\_\_\_\_ the subject.
3. Substitute into the original \_\_\_\_\_.
4. Remove ' on the variables.

### □ Learning Objective: [4.3.2] - Rotations around points

#### Key Takeaways

#### □ Rotation $\theta$ in the Anticlockwise Direction:

#### Rotation $\theta$ in the Anticlockwise Direction

$$\text{Transformation Matrix} = \begin{bmatrix} \phantom{0} & \phantom{0} \\ \phantom{0} & \phantom{0} \end{bmatrix}$$

□ **Rotation Around Any Point  $(a, b)$ :**

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} a \\ b \end{bmatrix} \right) + \begin{bmatrix} a \\ b \end{bmatrix}$$

○ The idea is that we:

1. Translate the points by  $(-a, -b)$  so that the centre becomes the \_\_\_\_\_.
2. Rotate the point around the origin using the transformation matrix  $\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$ .
3. \_\_\_\_\_ the points by  $(a, b)$  so that we go back to  $(a, b)$  being the centre.

□ **Learning Objective: [4.3.3] - Reflections in lines**

**Key Takeaways**

□ **Reflections Across a Line  $y = mx$ :**

**Reflection around  $y = mx = \tan(\theta)x$**

□  $\theta$  is the angle the reflection line meets with the  $x$ -axis.

***Transformation Matrix*** =  $\begin{bmatrix} \phantom{0} & \phantom{0} \\ \phantom{0} & \phantom{0} \end{bmatrix}$

- Reflection across a line  $y = mx + c$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix} \left( \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} 0 \\ c \end{bmatrix} \right) + \begin{bmatrix} 0 \\ c \end{bmatrix}$$

- The idea is that we:

1. Translate the points by  $(0, -c)$  so that the line  $y = mx + c$  becomes \_\_\_\_\_.
2. Reflect the point around  $y = mx$  using the transformation matrix  $\begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix}$ .
3. Translate the points by \_\_\_\_\_ so that we go back to the line  $y = mx + c$ .





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