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## VCE Specialist Mathematics ½ Transformations I [4.2] Workbook

### Outline:



#### Linear Transformations

Pg 2-12

- Introduction to Linear Transformations
- Unit Square
- Determinant and Area of Unit Square

#### Types of Transformations

Pg 13-33

- Dilations
- Shear
- Reflections around  $x$  and  $y$ -axis
- Projections
- Translations

#### Inverse Transformations

Pg 34-41

- Reversing Transformations
- Validity of Inverse Transformations

#### Composite Transformations

Pg 42-44

- Composite Transformations

### Learning Objectives:

- SM12 [4.2.1] - Using Matrices for Linear Transformations
- SM12 [4.2.2] - Dilations, Reflections, Translations, Shears and Projections
- SM12 [4.2.3] - Inverse Transformations
- SM12 [4.2.4] - Composite Transformations



## Section A: Linear Transformations

### Sub-Section: Introduction to Linear Transformations



#### Context: Linear Transformations

- Consider a point  $(1, 4)$ .
- What would the new  $x$ -value be if it's triple the current  $x$ -values plus double the current  $y$ -value?
- What would the new  $y$ -value be if it's double the current  $x$ -values minus half the current  $y$ -value?
- Hence, what would the new point be?

#### Linear Transformations



$$(x, y) \rightarrow (ax + by, cx + dy) = (x', y')$$

- The  $(x', y')$  represents the new points and is called an \_\_\_\_\_.
- Original point  $(x, y)$  is called the \_\_\_\_\_.

#### Space for Personal Notes

### Question 1

Find the image of the point  $(2, 1)$  under the transformation with rule  $(x, y) \rightarrow (3x - 5y, 2x - 4y)$ .

#### REMINDER: Matrix Multiplication

$$A \times B = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \times 3 + (-1) \times 1 \\ 1 \times 3 + 2 \times 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \end{bmatrix}$$

*Number of Columns of 1<sup>st</sup> Matrix = Number of Rows of 2<sup>nd</sup>*

- The answer will always be a matrix.

*How can we represent the transformation using matrices?*

#### Exploration: Matrices for Linear Transformations

- Consider the following matrix multiplication:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

- Evaluate the answer for the above multiplication!

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \text{Transformation Matrix}$$

**Question 2 Walkthrough.**

Consider a point  $(x, y)$  which is represented by the matrix  $\begin{bmatrix} x \\ y \end{bmatrix}$ .

Find the image given by  $\begin{bmatrix} -1 & 3 \\ 5 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ .

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**Question 3**

Consider a point  $(x, y)$  which is represented by the matrix  $\begin{bmatrix} x \\ y \end{bmatrix}$ .

Find the transformed point given by  $\begin{bmatrix} 3 & 2 \\ 2 & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ .

**NOTE:**  $\begin{bmatrix} 3 & 2 \\ 2 & -\frac{1}{2} \end{bmatrix}$  is called a transformation matrix.



**Discussion:** Considering the answer from above, why is it called linear transformation?



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**Question 4**

- a. Find the matrix of the linear transformation with the rule  $(x, y) \rightarrow (x - 2y, 3x + y)$ .
- b. Use the matrix to find the image of the point  $(2, 3)$  under the transformation.
- c. The image of a point  $(c, d)$  under the linear transformation is  $(2, 3)$ . Find  $c$  and  $d$ .

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Sub-Section: Unit Square



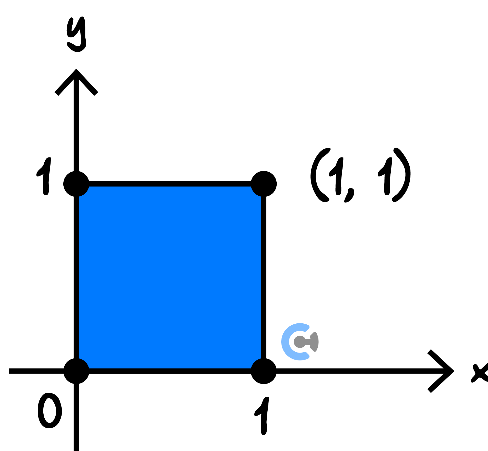
*What would be the best way to visualise the linear transformations?*



Transforming the Unit Square



Unit Square has a side length of 1.



- Unit square has a coordinate \_\_\_\_\_.
- Apply the transformation to  $(0, 0)$ ,  $(1, 0)$ ,  $(0, 1)$  and  $(1, 1)$  to see the effect of the transformations.

**NOTE:** We use unit squares to visualise how the transformation affects different points.



Discussion: Does it have to be a square then?

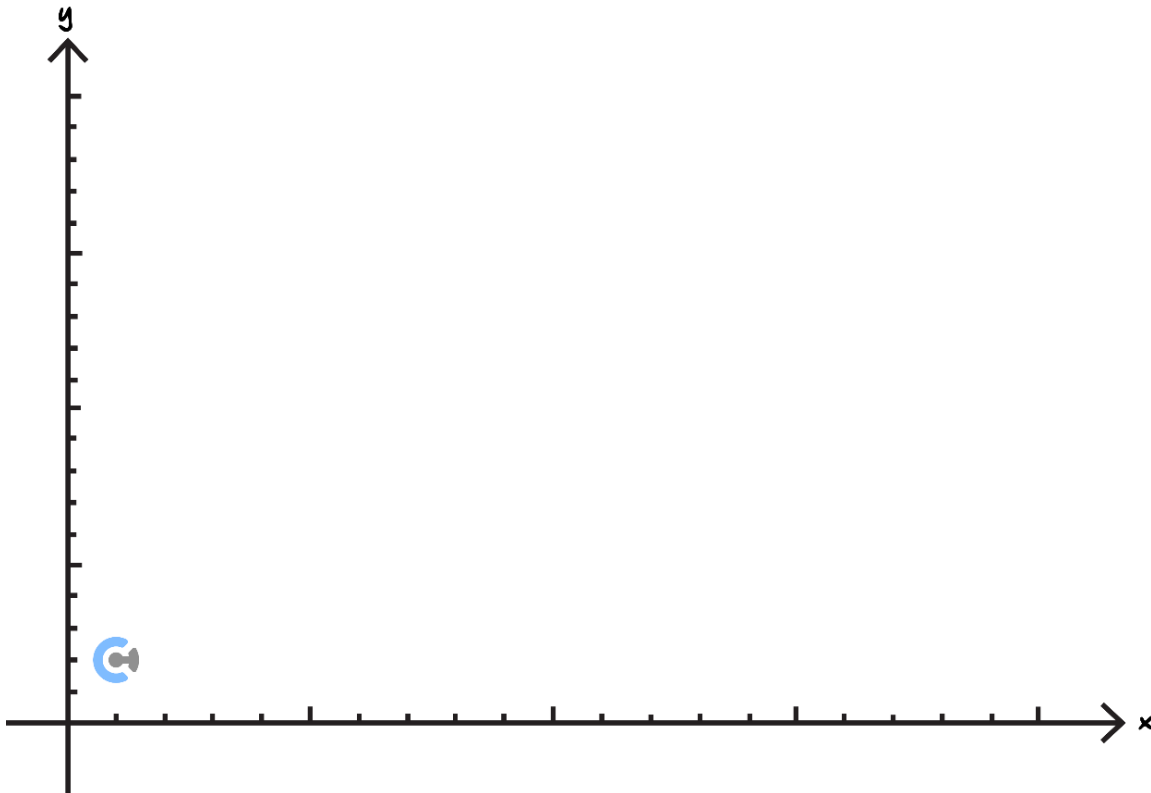


**Question 5 Walkthrough.**

A linear transformation is represented by the matrix  $A = \begin{bmatrix} 1 & 2 \\ 2 & 0 \end{bmatrix}$ .

- a. Find the image of the points of the unit square  $(0, 0)$ ,  $(1, 0)$ ,  $(0, 1)$  and  $(1, 1)$  under this transformation and write the image points as column vectors.

- b. Sketch the unit square and its image on the axes below.





**NOTE:** Unit square simply helps us to understand how the transformation affects the points.

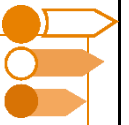


**Discussion:** How could we have done the linear transformations for  $(0, 0)$ ,  $(1, 0)$ ,  $(0, 1)$  and  $(1, 1)$  using one matrix multiplication?



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## Sub-Section: Determinant and Area of Unit Square



**REMINDER:** Determinant of a  $2 \times 2$  Matrix



$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\det(A) = ad - bc$$

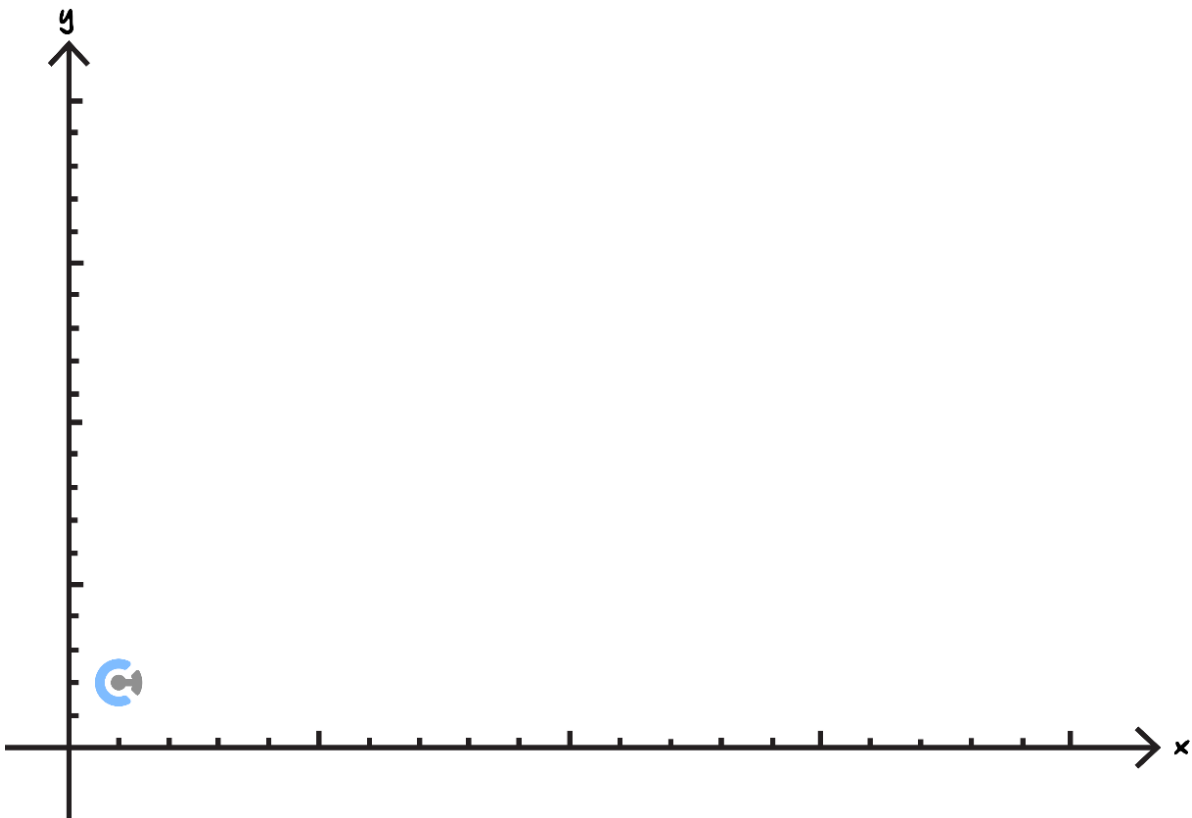
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**Question 6 Walkthrough.**

A linear transformation is represented by the transformation matrix  $A = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$ .

- a. Find the image of the points of the unit square  $(0, 0)$ ,  $(1, 0)$ ,  $(0, 1)$  and  $(1, 1)$  under this transformation and write the image points as column vectors.

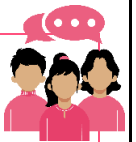
- b. Sketch the unit square and its image on the axes below.



c. State the area of the unit square and its image.

d. Find the determinant of the transformation matrix  $A = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$ .

**Discussion:** What do you notice? What does the determinant of the transformation matrix tell us?



### Determinant of Transformation Matrix



➤ Given that  $A$  = Transformation matrix.

$$\text{Area of the image} = |\det(A)| \times \text{Area of the pre image}$$

➤ Determinant could be \_\_\_\_\_ hence we put the modulus.

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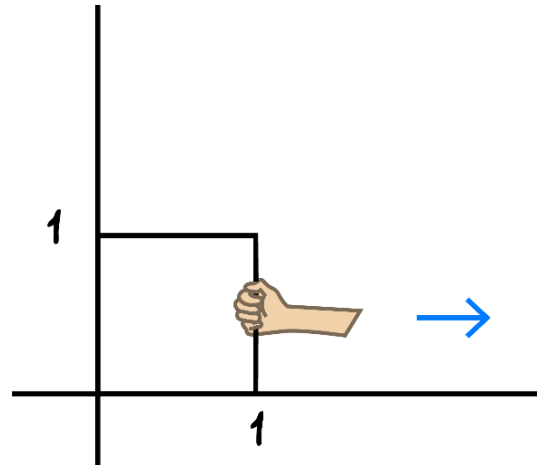
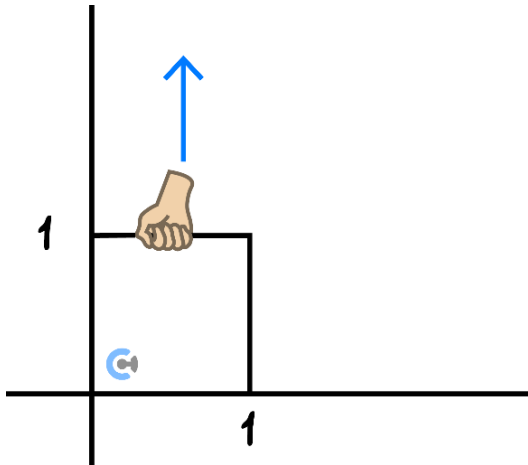
## Section B: Types of Transformations

### Sub-Section: Dilations

*What do dilations do?*

#### Exploration: Understanding Dilations

- Let's say Krish is bored that the unit square has a length of 1, and decides to stretch the unit square from the  $x$  and the  $y$ -axis.

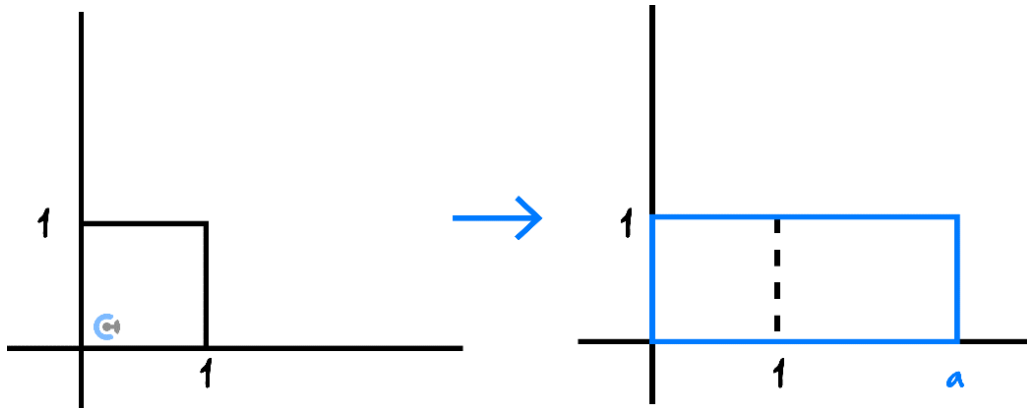


- From the diagram above, state which one is dilation from the  $x$ -axis and  $y$ -axis.
- Which variable ( $x$  or  $y$ ) does the dilation from the  $x$ -axis change?
- Which variable ( $x$  or  $y$ ) does the dilation from the  $y$ -axis change?

Space for Personal Notes



### Dilation from the y-axis



Dilation by a factor  $a$  from the  $y$ -axis.

➤ Dilation from the  $y$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} a & 0 \\ 0 & 1 \end{bmatrix}$$

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**a.** State the transformation matrix for dilation by a factor of 3 from the  $y$ -axis.

**b.** Apply the transformation matrix found in **part a.** to the coordinate  $(x, y)$ .

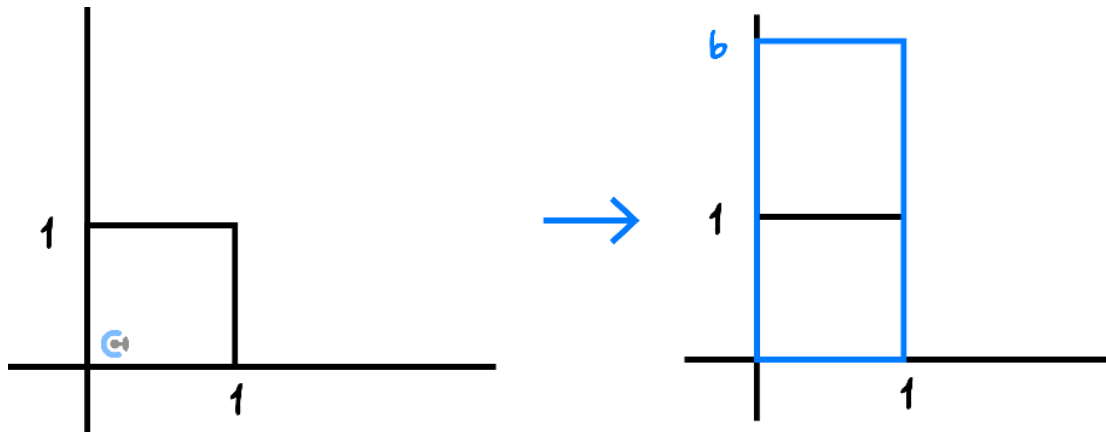
**NOTE:** The  $x$ -value is tripled for dilation by a factor 3 from the  $y$ -axis.



### Space for Personal Notes



### Dilation from the $x$ -axis



**Dilation by a factor  $b$  from the  $x$ -axis.**

► Dilation from the  $x$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ 0 & b \end{bmatrix}$$

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**a.** State the transformation matrix for dilation by factor 2 from the  $x$ -axis.

**b.** Apply the transformation matrix found in **part a.** to the coordinate  $(x, y)$ .

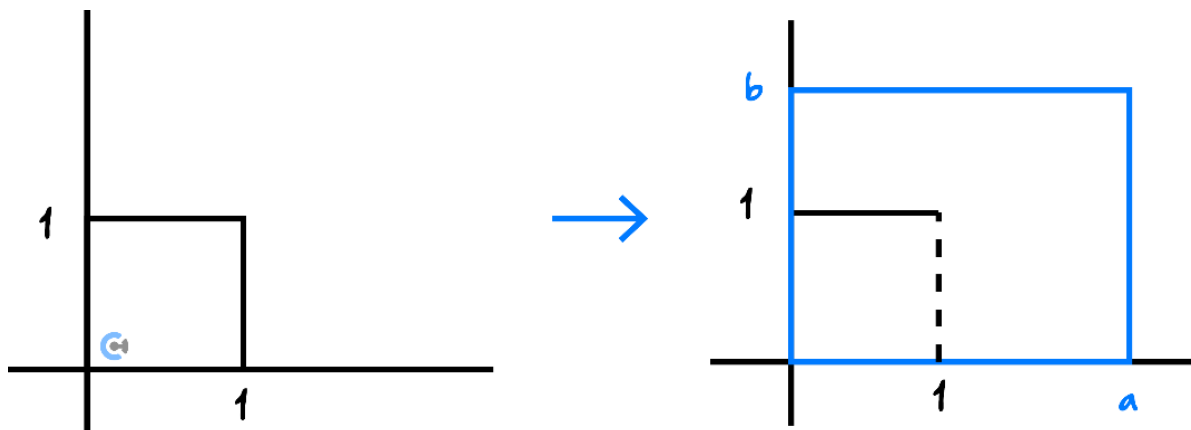


### Space for Personal Notes

*Let's combine.*



### Dilation and its Transformation Matrix



Dilation by a factor  $a$  from the  $y$ -axis.

Dilation by a factor  $b$  from the  $x$ -axis.

$$\text{Transformation Matrix} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

**Discussion:** Find the determinant of  $\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$ . Does it make sense?



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## Sub-Section: Shear



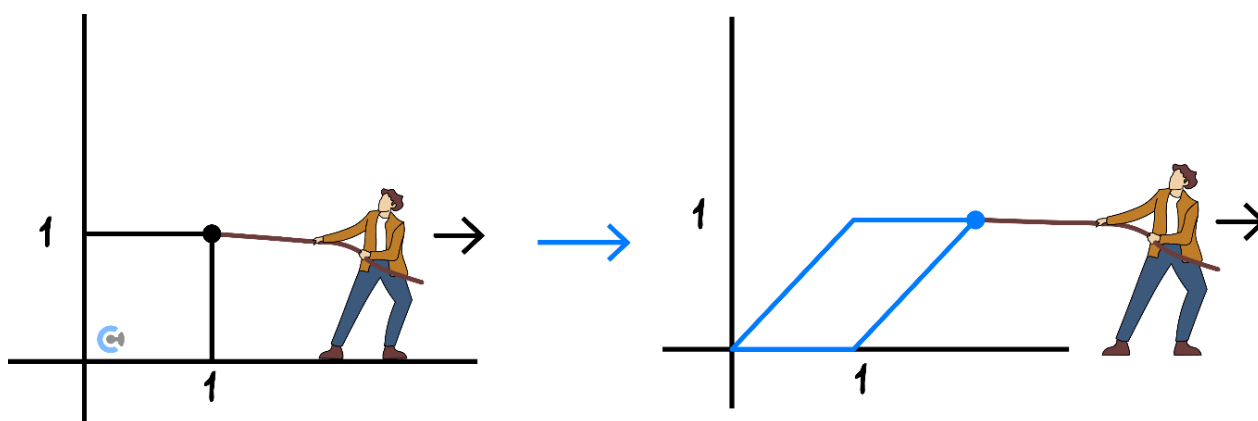
*What about "shear"?*



### Exploration: Understanding Shear Parallel to the $x$ -axis



- Let's bring Krish back again.
- He ties a rope on the point  $(1,1)$  of the "malleable" unit square and pulls it parallel to  $x$ -axis.

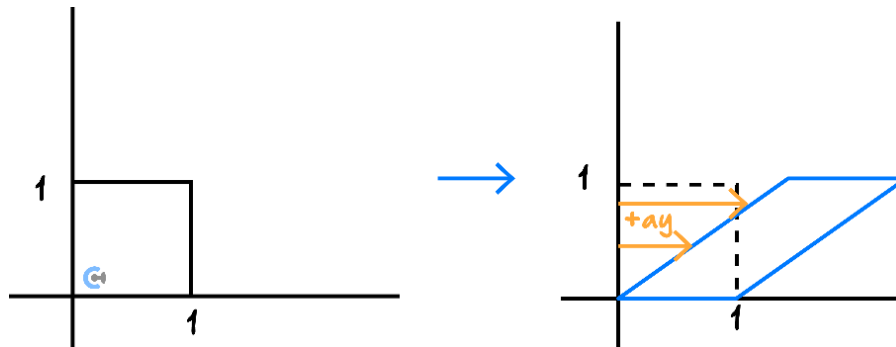


- Which variable ( $x$  or  $y$ ) would change?
- Would all the points move the same distance parallel to the  $x$ -axis?
- Does the point move more if they are further from the  $x$ -axis or closer?
- Therefore, what does the change in  $x$ -value correspond to?

**NOTE:** The  $x$ -value changes with respect to how big their  $y$ -value is.



### Shear Parallel to the $x$ -axis



Shear of a factor  $a$  parallel to the  $x$ -axis.

➤ Shear parallel to  $x$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}$$

Space for Personal Notes

a. State the transformation matrix for the shear of a factor 3 parallel to the  $x$ -axis.

**b.** Apply the transformation matrix found in **part a.** to the coordinate  $(x, y)$ .



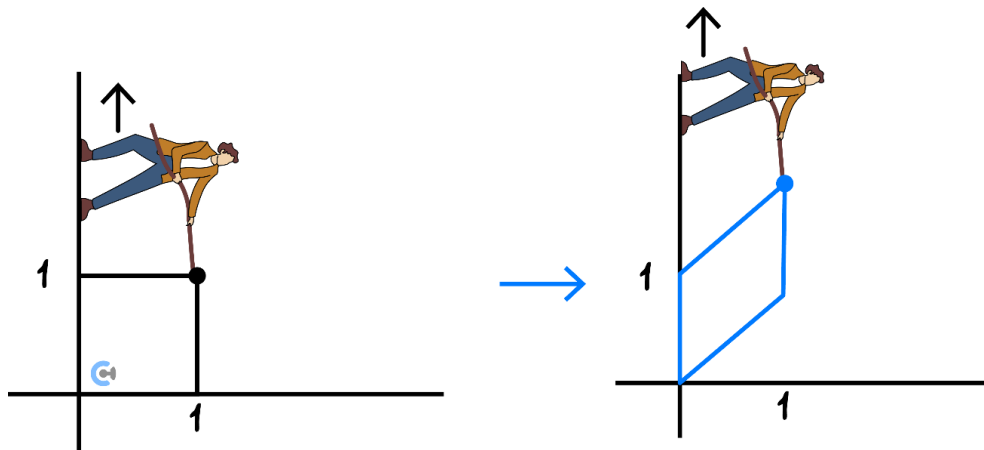
### Space for Personal Notes

*What about in the direction of the y-axis?*



**Exploration: Understanding Shear Parallel to the y-axis**

- Let's bring Krish back again  $\times 2$ .
- He ties a rope on the point  $(1, 1)$  of the "malleable" unit square and pulls it parallel to y-axis.



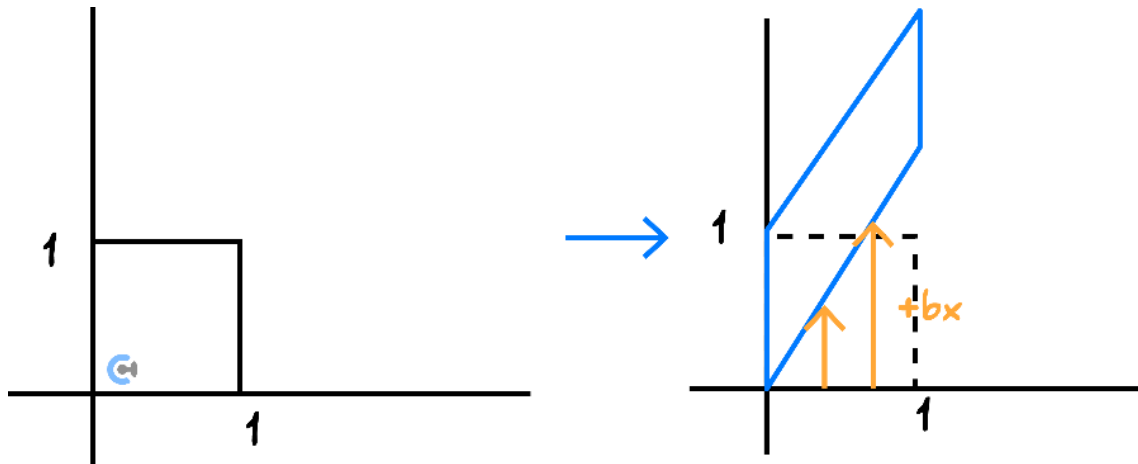
- Which variable ( $x$  or  $y$ ) would change?
- Would all the points move the same distance parallel to the y-axis?
- Does the point move more if they are further from the y-axis or closer?
- Therefore, what does the change in  $y$ -value correspond to?

**NOTE:** The  $y$ -value changes with respect to how big their  $x$ -value is.





### Shear Parallel to the $y$ -axis



Shear of a factor  $b$  parallel to the  $y$ -axis.

➤ Shear parallel to  $y$ -axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ b & 1 \end{bmatrix}$$

Space for Personal Notes

**Question 10**

- a. State the transformation matrix for the shear of a factor 2 parallel to the  $y$ -axis.
  
  
  
  
  
  
  
  
  
  
- b. Apply the transformation matrix found in **part a.** to the coordinate  $(x, y)$ .

**NOTE:** The  $y$ -value is added by doubling the  $x$ -value.



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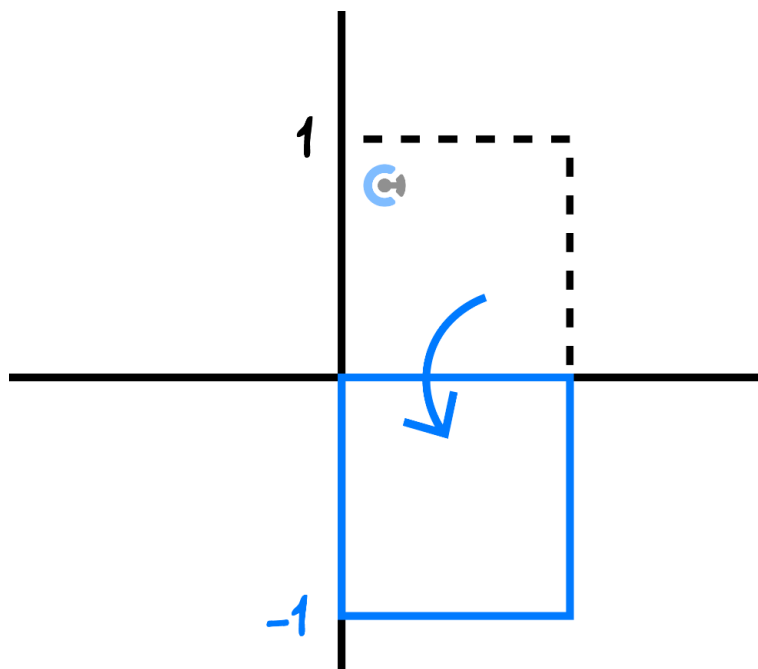
## Sub-Section: Reflections around $x$ and $y$ -axis



**Discussion:** If you reflect something around the  $x$ -axis, what would happen? What about the  $y$ -axis?



### Reflection around $x$ -axis



Reflection in the  $x$ -axis.

➤ Reflection in the  $x$ -axis changes the \_\_\_\_\_.

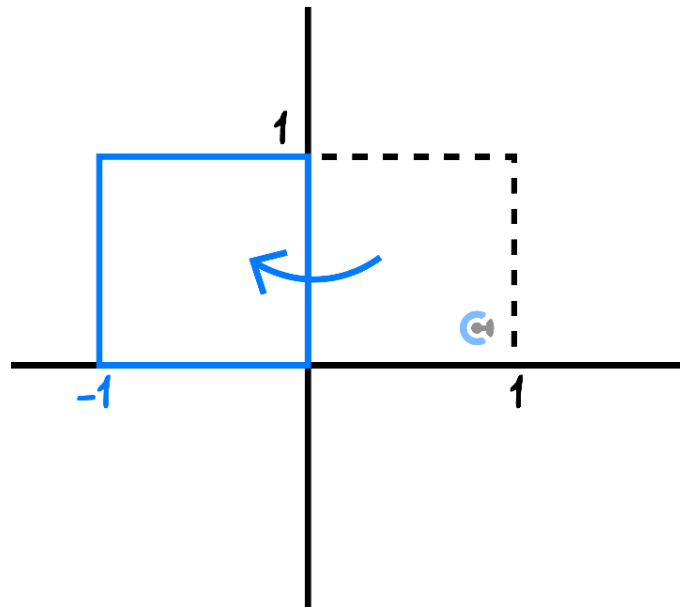
$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Space for Personal Notes

*Now around y-axis.*



### Reflection around y-axis



### Reflection in the y-axis

► Reflection in the y-axis changes the \_\_\_\_\_.

$$\text{Transformation Matrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

Space for Personal Notes

### Question 11

- a.** State the transformation matrix for reflection in both  $x$  and  $y$ -axis.
- b.** Apply the transformation matrix found in **part a.** to the coordinate  $(x, y)$ .

**Discussion:** Consider the size of the determinant of the reflection transformation matrix. Does it make sense?



### Space for Personal Notes

Sub-Section: Projections



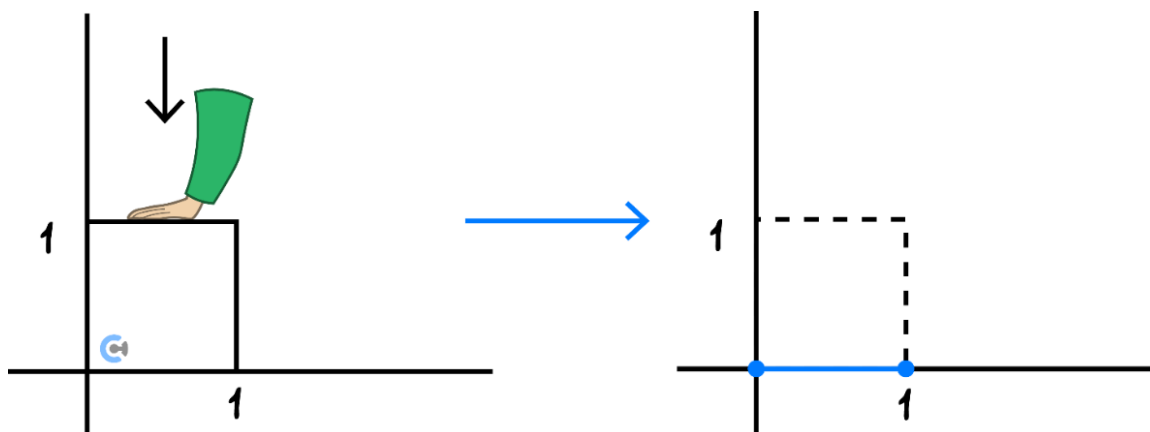
*What about “projections”?*



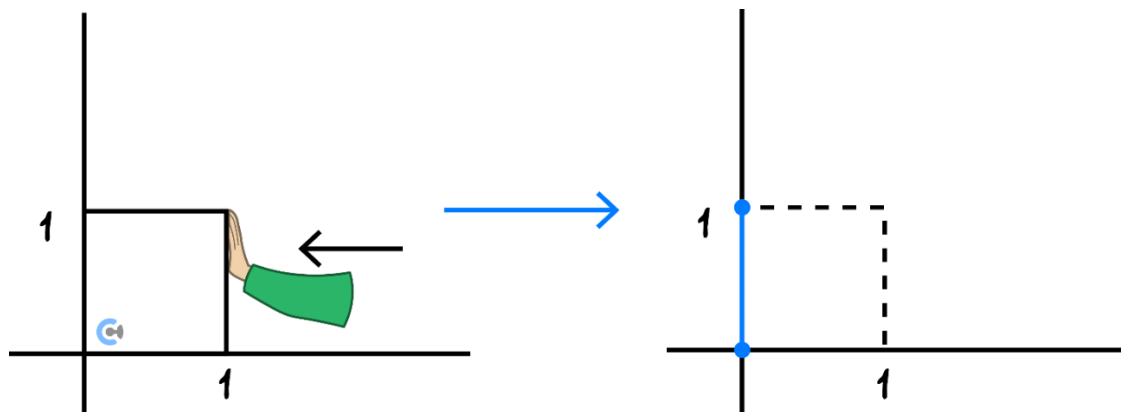
Exploration: Understanding Projection



- Bringing Krish back again  $\times 3$ .
- He wants to squish the unit square onto the  $x$ -axis.

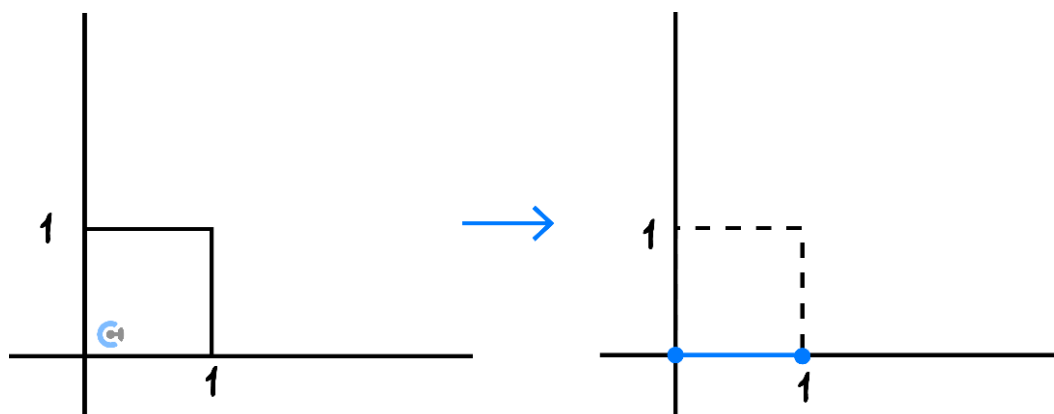


- What would happen?
- Would this be a “projection” onto the  $x$ -axis or  $y$ -axis?



- How about now?
- What would happen?
- Would this be a "projection" onto the  $x$ -axis or  $y$ -axis?

## Projections

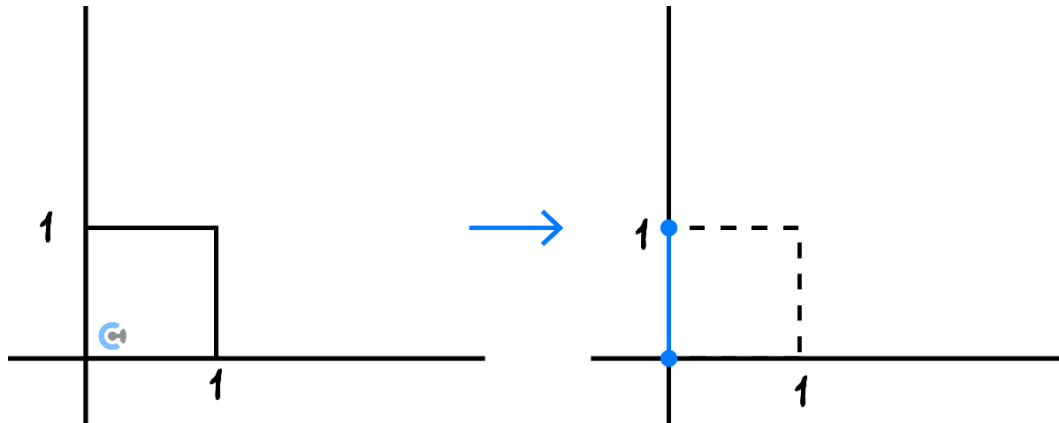


Projection onto the  $x$ -axis:

- The \_\_\_\_\_ becomes 0.

$$\text{Transformation Matrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$





Projection onto the  $y$ -axis:

► The \_\_\_\_\_ becomes 0.

$$\text{Transformation Matrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Space for Personal Notes

### Question 12

- a. State the transformation matrix for projection onto  $y$ -axis.
- b. Find the image of  $(2, 1)$  after the transformation projection onto  $y$ -axis.

**NOTE:** Projection onto  $y$ -axis only keeps the  $y$ -value.



**Discussion:** Consider the determinant of the projection transformation matrix. Does it make sense?



### Space for Personal Notes

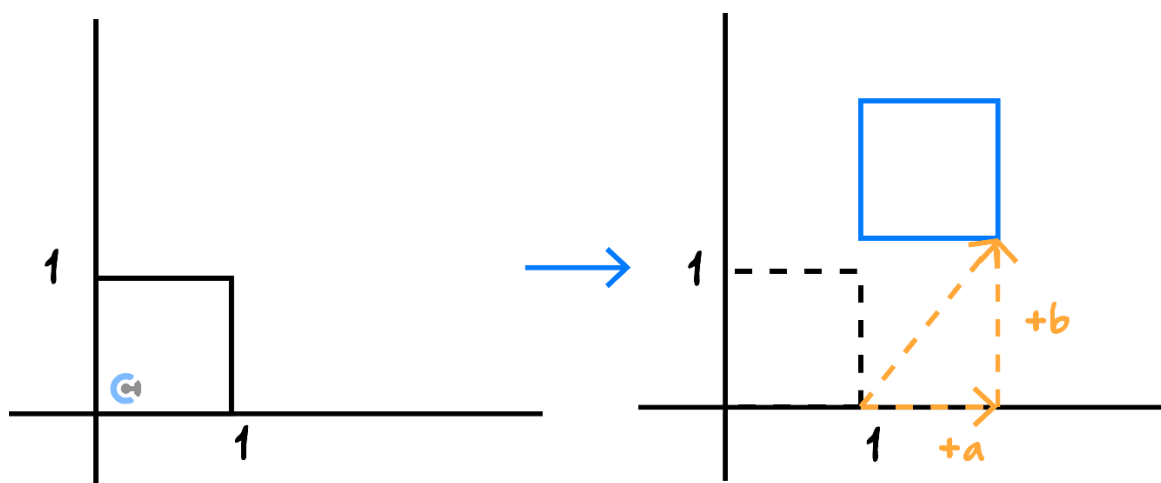
Sub-Section: Translations



*Now translations!*



Translation



- Translation simply moves the point.

Translation  $a$  units in the positive direction of the  $x$ -axis.

Translation  $b$  units in the positive direction of the  $y$ -axis.

- We simply add/subtract the translation value to  $x$  and  $y$ .

$$\text{Transformation: } \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} a \\ b \end{bmatrix}$$

Space for Personal Notes



**Question 13**

Consider the point  $(4, 1)$ .

The point has been translated 2 units in the positive direction of the  $x$ -axis and translated 3 units in the negative direction of the  $y$ -axis.

Find the image using matrices.

Space for Personal Notes

## Section C: Inverse Transformations

### Sub-Section: Reversing Transformations

**REMINDER:** Inverse of a  $2 \times 2$  Matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

- Inverse only exists for a square matrix.
- Matrix that has an inverse is called \_\_\_\_\_.

Space for Personal Notes

### Question 14

Consider a transformation matrix given by  $A = \begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix}$ .

- a. Find the image of  $(2, 3)$  after applying transformation  $A$ .
- b. Find the inverse matrix of  $A$ .
- c. Find the image of  $(7, 3)$  after applying transformation  $A^{-1}$ .

**TIP:** Take the factor out and multiply it afterwards.



**Discussion:** From the previous question, what do we do to reverse a transformation?



*Let's also prove this using matrix algebra!*



### Exploration: Algebraic Proof of Inverse Transformation

- Consider:

$$X' = AX$$

- Multiply  $A^{-1}$  on both sides.

NOTE: We always multiply the matrices on the LHS.

- What does  $AA^{-1}$  equal to?

- What does  $IA$  always equal to?

- We can multiply the inverse transformation matrix by the image to go back to the pre-image.

### Inverse Transformation



$$\text{If } X' = AX \text{ then } A^{-1}X' = X.$$

- Multiply the inverse transformation matrix to the image to go back to the pre-image.

**Question 15**

A point  $(x, y)$  has been transformed by  $A = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}$  and the image was given by  $(2, 1)$ .

**a.** Find  $A^{-1}$ .

**b.** Hence, find the point  $(x, y)$ .

Space for Personal Notes

## Sub-Section: Validity of Inverse Transformations



**Discussion:** Do all matrices have an inverse?



**REMINDER:** Determinant of a  $2 \times 2$  Matrix



$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\det(A) = ad - bc$$

- If the determinant equals \_\_\_\_\_, then  $A$  does not have an inverse.
- $A$  is not \_\_\_\_\_.

**Discussion:** If a transformation matrix  $A$  does not have an inverse  $A^{-1}$ , how can we reverse the transformation under  $A$ ?



Space for Personal Notes

*Why can't some transformations be reversed?*



### Question 16

Consider a transformation matrix given by  $A = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$ .

- a. Find the  $\det(A)$ .
- b. Find the image of  $(3, 4)$  under the transformation given by  $A$ .
- c. Find the image of  $(2, 5)$  under the transformation given by  $A$ .

### Space for Personal Notes



**Discussion:** Looking at the question above, how can we reverse the transformation from the image: (7, 14)?



### Non-Invertible Matrix and Inverse Transformations

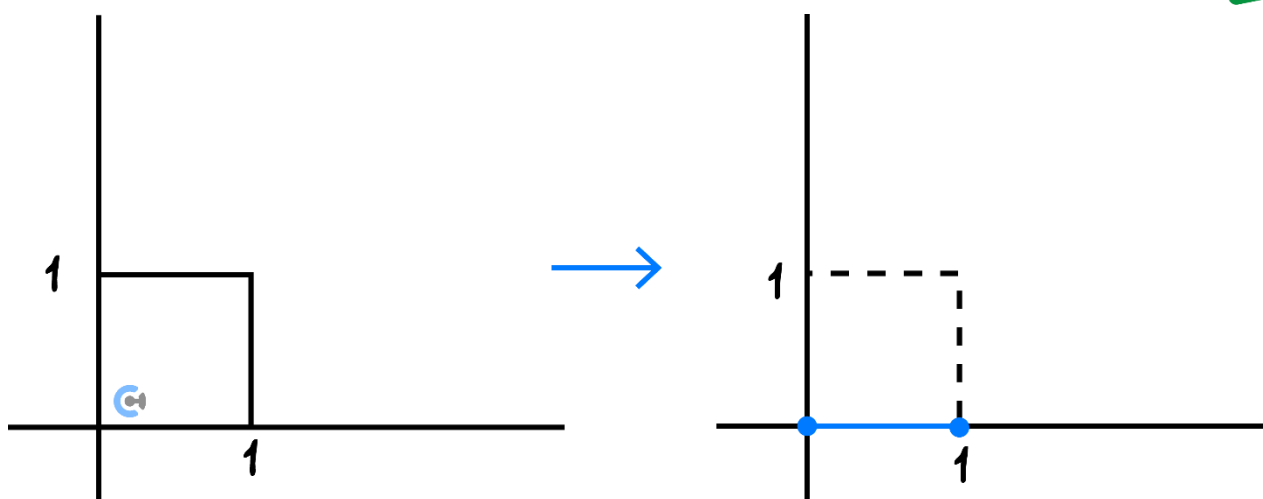
$$X' = AX$$

*If  $\det(A) = 0$ , then  $X$  cannot be solved as  $A^{-1}$  is undefined.*

- The original point cannot be solved if the inverse matrix does not exist.
- The transformation cannot be \_\_\_\_\_ when \_\_\_\_\_.
- It happens as the image can be achieved from multiple pre-images.



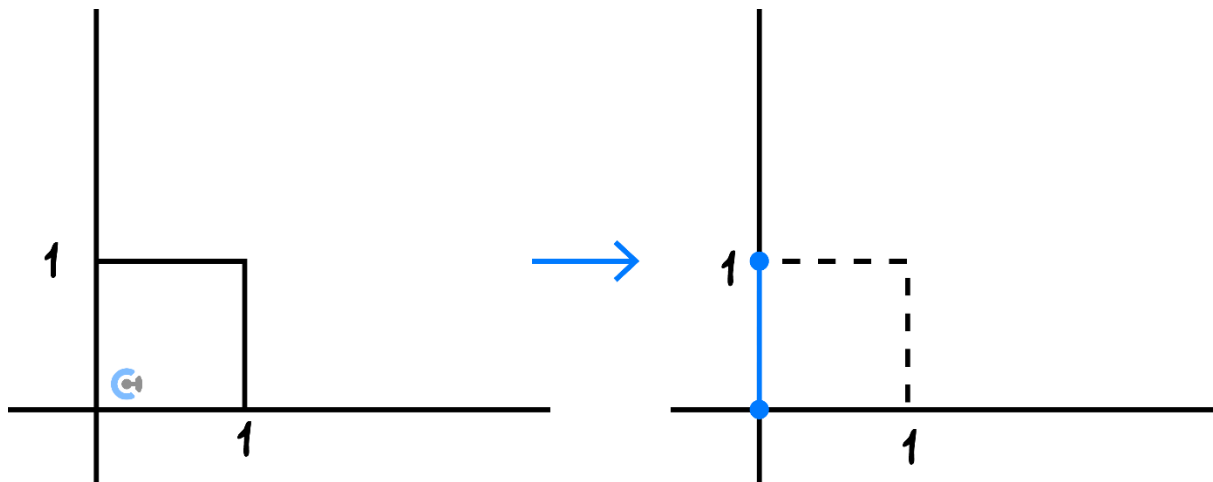
### Active Recall: Projection



Projection onto  $x$ -axis:

*Transformation Matrix = \_\_\_\_\_*





Projection onto  $y$ -axis:

*Transformation Matrix* = \_\_\_\_\_

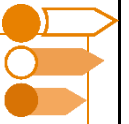
**Discussion:** Consider the determinant of the projection transformation matrix. Can any projection transformation be reversed? Does that make sense?



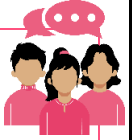
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## Section D: Composite Transformations

### Sub-Section: Composite Transformations



Discussion: How do we do multiple transformations?



### Composite Transformations



➤ For transformation under  $A$  and  $B$  respectively,

$$X' = BAX$$

➤ Always multiply the next transformation matrix on the \_\_\_\_\_.

Space for Personal Notes

**Question 17 Walkthrough.**

- a. State the transformation matrix for dilation by factor 2 from the  $x$ -axis and reflection in the  $x$ -axis.
- b. Apply the transformation matrix found in **part a.** to the coordinate  $(3, 1)$ .

Space for Personal Notes

*Your turn!*

**Question 18**

- a. State the transformation matrix for dilation by factor 3 from the  $x$ -axis, shear of factor 3 parallel to the  $y$ -axis and reflection in the  $y$ -axis.
- b. Hence, apply the transformation “dilation by factor 3 from the  $x$ -axis, shear of factor 3 parallel to the  $y$ -axis and reflection in the  $y$ -axis” to the coordinate  $(-2, 5)$ .

**Space for Personal Notes**



## Contour Check

### ☐ Learning Objective: [4.2.1] - Using matrices for linear transformations

#### Key Takeaways

#### ☐ Linear Transformations:

$$(x, y) \rightarrow (ax + by, cx + dy) = (x', y')$$

- ☐ The  $(x', y')$  represents the new points and is called an \_\_\_\_\_.
- ☐ Original point  $(x, y)$  is called the \_\_\_\_\_.

#### ☐ Matrices for Linear Transformations:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \underline{\hspace{5cm}}$$

#### ☐ Determinant of Transformation Matrix:

- ☐ Given that  $A$  = Transformation matrix.

$$\text{Area of the image} = |\det(A)| \times \text{Area of the pre image}$$

- ☐ Determinant could be \_\_\_\_\_ hence we put the modulus.

- **Learning Objective: [4.2.2] - Dilations, reflections, translations, shears and projections**

### Key Takeaways

- Dilation from the  $y$ -axis:

Dilation by a factor  $a$  from the  $y$ -axis.

- Dilation from the  $y$ -axis changes the \_\_\_\_\_.

*Transformation Matrix* = \_\_\_\_\_

- Dilation from the  $x$ -axis:

Dilation by a factor  $b$  from the  $x$ -axis.

- Dilation from the  $x$ -axis changes the \_\_\_\_\_.

*Transformation Matrix* = \_\_\_\_\_

- Dilation and its Transformation Matrix:

Dilation by a factor  $a$  from the  $y$ -axis.

Dilation by a factor  $b$  from the  $x$ -axis.

*Transformation Matrix* = \_\_\_\_\_

- Shear Parallel to the  $x$ -axis:

Shear of a factor  $a$  parallel to the  $x$ -axis.

- Shear parallel to  $x$ -axis changes the \_\_\_\_\_.

*Transformation Matrix* = \_\_\_\_\_

☐ Shear Parallel to the  $y$ -axis:

Shear of a factor  $b$  parallel to the  $y$ -axis.

- ☐ Shear parallel to  $y$ -axis changes the \_\_\_\_\_.

*Transformation Matrix* = \_\_\_\_\_

☐ Reflection around  $x$ -axis:

Reflection in the  $x$ -axis:

- ☐ Reflection in the  $x$ -axis changes the \_\_\_\_\_.

*Transformation Matrix* = \_\_\_\_\_

☐ Reflection around  $y$ -axis:

Reflection in the  $y$ -axis:

- ☐ Reflection in the  $y$ -axis changes the \_\_\_\_\_.

*Transformation Matrix* = \_\_\_\_\_

☐ Projections:

Projection onto the  $x$ -axis:

- ☐ The \_\_\_\_\_ becomes 0.

*Transformation Matrix* = \_\_\_\_\_

Projection onto the  $y$ -axis:

- ☐ The \_\_\_\_\_ becomes 0.

*Transformation Matrix* = \_\_\_\_\_

□ **Translation:**

- Translation simply moves the point.

**Translation  $a$  units in the positive direction of the  $x$ -axis.**

**Translation  $b$  units in the positive direction of the  $y$ -axis.**

- We simply add/subtract the translation value to  $x$  and  $y$ .

***Transformation:*** 
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} a \\ b \end{bmatrix}$$

□ **Learning Objective: [4.2.3] - Inverse transformations**

**Key Takeaways**

□ **Inverse Transformation:**

**If  $X' = AX$  then  $X =$  \_\_\_\_\_.**

- Multiply the inverse transformation matrix to the image to go back to the \_\_\_\_\_.

□ **Non-Invertible Matrix and Inverse Transformations:**

$$X' = AX$$

***if  $\det(A) = 0$ , then  $X$  cannot be solved as  $A^{-1}$  is undefined.***

- The original point cannot be solved if the inverse matrix does not exist.
- The transformation cannot be \_\_\_\_\_ when \_\_\_\_\_.
- It happens as the image can be achieved from multiple pre-images.



□ **Learning Objective: [4.2.4] - Composite transformations**

**Key Takeaways**

- For transformation under  $A$  and  $B$  respectively:

$$X' = BAX$$

- Always multiply the next transformation matrix on the \_\_\_\_\_.



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## VCE Specialist Mathematics ½

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